

Linear algebra: diagonalization.

矩陣可視為一種變換

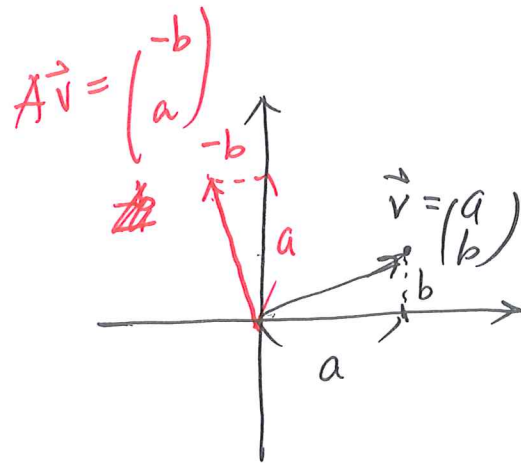
$$\vec{v} \mapsto A\vec{v}$$

\vec{v} 變成 $A\vec{v}$.

Exmp. $A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$

$$\begin{pmatrix} a \\ b \end{pmatrix} \mapsto \begin{pmatrix} -b \\ a \end{pmatrix}$$

逆時針轉 90° .



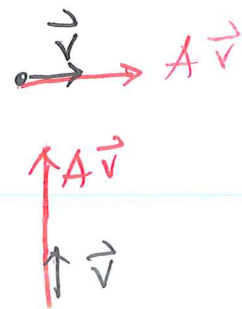
Exmp. $A = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$

$$\begin{pmatrix} a \\ b \end{pmatrix} \mapsto \begin{pmatrix} 2a \\ 3b \end{pmatrix}$$

x 方向 $\times 2$, y 方向 $\times 3$.

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} 2 \\ 0 \end{pmatrix} = 2 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} 0 \\ 3 \end{pmatrix} = 3 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$



Suppose for some $\vec{v} \in \mathbb{R}^n$, $\vec{v} \neq \vec{0}$, $\lambda \in \mathbb{R}$

$$A\vec{v} = \lambda\vec{v}$$

特徵向量

Then \vec{v} is an eigenvector with respect to

the eigenvalue λ

特徵值.

$$\vec{v} \longmapsto A\vec{v} = \lambda \vec{v}.$$

\vec{v} 經過 A 變換以後 被放大 λ 倍.

• 若 $A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$, 則 $A^T = \begin{pmatrix} a_{11} & \dots & a_{m1} \\ a_{12} & & a_{m2} \\ \vdots & & \vdots \\ a_{1n} & \dots & a_{mn} \end{pmatrix}$

transpose
轉置.

Exmp. $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$, $A^T = \begin{pmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{pmatrix}$

$B = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix}$, $B^T = \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} = B.$

• A matrix A is symmetric if $A = A^T$.

Thm. Let A be a $n \times n$ symmetric matrix.

Then there are $\vec{v}_1, \dots, \vec{v}_n \in \mathbb{R}^n$
 $\lambda_1, \dots, \lambda_n \in \mathbb{R}$

such that $\begin{cases} \bullet A \vec{v}_i = \lambda_i \vec{v}_i \text{ for all } i. \end{cases}$

$\begin{cases} \bullet \vec{v}_i \cdot \vec{v}_i = 1 \text{ for all } i \leftarrow \text{unit length} \\ \bullet \vec{v}_i \cdot \vec{v}_j = 0 \text{ for all } i \neq j \leftarrow \text{mutually orthogonal.} \end{cases}$

Exmp. $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$, $\vec{v}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ or $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\vec{v}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$, $\vec{v}_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$

- We say $\{\vec{v}_1, \dots, \vec{v}_n\}$ is orthonormal if each \vec{v}_i has unit length and they are mutually orthogonal.

- If $\{\vec{v}_1, \dots, \vec{v}_n\}$ is orthogonal and $A = \begin{pmatrix} | & & | \\ \vec{v}_1 & \dots & \vec{v}_n \\ | & & | \end{pmatrix}$,

then $A^T A = A A^T = I$ ← 單位矩陣. $\begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$

$$\underbrace{\begin{pmatrix} - & \vec{v}_1 & - \\ & \vdots & \\ - & \vec{v}_n & - \end{pmatrix}}_{A^T} \underbrace{\begin{pmatrix} | & & | \\ \vec{v}_1 & \dots & \vec{v}_n \\ | & & | \end{pmatrix}}_A = (\vec{v}_i \cdot \vec{v}_j) = \underbrace{\begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}}_I$$

$$A^T A = I \Rightarrow A^T = \underbrace{A^{-1}}_{\text{inverse, 反矩陣}} \Rightarrow A A^T = I.$$

Properties: $(I \sim 1, A^{-1} \sim \frac{1}{A})$

- $I \cdot A = A, A \cdot I = A.$

- $AB = AC \Rightarrow A^{-1}AB = A^{-1}AC$

$$\Rightarrow IB = IC \Rightarrow B = C.$$

- $BA = CA \Rightarrow BAA^{-1} = CAA^{-1}$

$$\Rightarrow BI = CI \Rightarrow B = C.$$

- $BC = BAA^{-1}C = BA^{-1}AC$

Consequence of eigenvectors.

A = sym matrix

v_1, \dots, v_n ^{vectors} ~~eigenvalues~~

$\lambda_1, \dots, \lambda_n$ eigenvalues.

$$\begin{cases} A\vec{v}_i = \lambda_i \vec{v}_i & \text{for all } i, \\ \{\vec{v}_1, \dots, \vec{v}_n\} & \text{is orthonormal.} \end{cases}$$

$$\Rightarrow \text{Let } Q = \begin{pmatrix} | & & | \\ \frac{1}{\sqrt{}} \vec{v}_1 & \dots & \frac{1}{\sqrt{}} \vec{v}_n \\ | & & | \end{pmatrix} \Rightarrow Q^T Q = Q Q^T = I$$

$$\Downarrow \\ Q^T = Q^{-1}$$

$$\begin{aligned} A Q &= A \begin{pmatrix} | & & | \\ \frac{1}{\sqrt{}} \vec{v}_1 & \dots & \frac{1}{\sqrt{}} \vec{v}_n \\ | & & | \end{pmatrix} = \begin{pmatrix} | & & | \\ A\vec{v}_1 & \dots & A\vec{v}_n \\ | & & | \end{pmatrix} \\ &= \begin{pmatrix} | & & | \\ \lambda_1 \vec{v}_1 & \dots & \lambda_n \vec{v}_n \\ | & & | \end{pmatrix} = \begin{pmatrix} | & & | \\ \frac{1}{\sqrt{}} \vec{v}_1 & \dots & \frac{1}{\sqrt{}} \vec{v}_n \\ | & & | \end{pmatrix} \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & & \\ \vdots & & \ddots & \\ 0 & \dots & 0 & \lambda_n \end{pmatrix} \\ &= Q \cdot D \end{aligned}$$

↑
對角線矩陣

$$AQ = QD \Leftrightarrow Q^{-1}AQ = D$$

$$\Leftrightarrow A = QDQ^{-1}$$

對角化.

⚡ $Q^{-1} = Q^T$ in this case.

Exmp. (對角化的好處).

$$\text{If } A = QDQ^{-1},$$

$$\text{then } A^{100} = (QDQ^{-1})(QDQ^{-1}) \dots (QDQ^{-1})$$

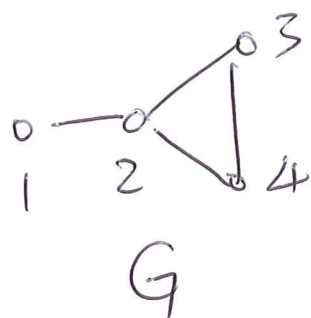
$$= QD(Q^{-1}Q)D(Q^{-1}Q) \dots (Q^{-1}Q)DQ^{-1}$$

$$= QD^{100}Q^{-1}$$

Spectral embedding

Recall $L(G)_{ij} = \begin{cases} \deg(i) & \text{if } i=j \\ -1 & \text{if } i \sim j \leftarrow ij \text{ 相邻} \\ 0 & \text{o.w.} \end{cases}$

Laplacian matrix.



$$\rightarrow \begin{pmatrix} 1 & -1 & 0 & 0 \\ -1 & 3 & -1 & -1 \\ 0 & -1 & 2 & -1 \\ 0 & -1 & -1 & 2 \end{pmatrix}$$

$L(G)$

Algorithm graph dimension

Input: G, d

Output: positions of vertices of G in \mathbb{R}^d

1. Compute $L(G)$.

2. Compute $\{\vec{v}_1, \dots, \vec{v}_n\}$, the orthonormal eigenvectors.
 $\lambda_1, \dots, \lambda_n$

3. Let $Y = \begin{pmatrix} 1 & \dots & 1 \\ \vec{v}_2 & \dots & \vec{v}_{d+1} \\ 1 & \dots & 1 \end{pmatrix} \left\{ \begin{array}{l} d \text{ 个} \\ n \text{ 维} \end{array} \right\} = \begin{pmatrix} -\vec{y}_1 & \dots \\ \vdots & \\ -\vec{y}_n & \dots \end{pmatrix} \left\{ \begin{array}{l} d \text{ 维} \\ n \text{ 个} \end{array} \right\}$

4. The positions of vertex i is \vec{y}_i .