

Liapunov-Schmidt reduction

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1 Tools.

Definition 1. Let X and Y be Banach spaces. A bounded linear operator $L : X \rightarrow Y$ is called *Fredholm* if the following two conditions hold.

- (a) $\text{Ker}L$ is a finite-dimensional subspace of X .
- (b) $\text{Range}L$ is a closed subspace of Y of finite codimension.

Definition 2. If L is Fredholm, the *index* of L is the integer $i(L) = \dim(\text{ker}L) - \text{codim}(\text{range}L)$.

Proposition 3. If $L : X \rightarrow Y$ is Fredholm, then there exists closed subspaces M and N of X and Y , respectively, such that

- (a) $X = \text{ker}L \oplus M$ and (b) $Y = N \oplus \text{range}L$.

Remark 4. In the following discussion, we assume L is *Fredholm* and its index is zero. By the definition of the index, it is easy to see that $\dim(\text{ker}L) = \dim N$, where N is the subspace of Y introduced in the proposition 3. If $\text{ker}L = \{0\}$, then L is onto and hence, by the closed graph theorem, L is invertible. Thus, we have the following implication for Fredholm operators of index zero: If $\text{ker}L = \{0\}$, then L is invertible.

2 Liapunov-Schmidt reduction.

Let $\Phi : X \times \mathbb{R}^{k+1} \rightarrow Y$, $\Phi(0,0) = 0$ be a smooth mapping between Banach spaces. We want to use the Liapunov-Schmidt reduction to solve the equation $\Phi(u, \alpha) = 0$ for u as a function of α near $(0,0)$. Let L be the differential of Φ at the origin; in symbols

$$Lu = \lim_{h \rightarrow 0} \frac{\Phi(u, 0) - \Phi(0, 0)}{h} .$$
 (note that the linear operator L is the Frechet derivative of Φ)

We assume that L is the Fredholm operator with index zero.

We have the L-S reduction in the following several steps :

1. Decompose X and Y :
 - (a) $X = \ker L \oplus M$.
 - (b) $Y = N \oplus \text{range} L$.

***Reason:** The hypothesis that L is Fredholm guarantees that the above splittings are possible. Moreover, $\ker L$ and N are finite-dimensional.
2. Split the equation $\Phi(u, \alpha) = 0$ into an equivalent pair of the equations:
 - (a) $E\Phi(u, \alpha) = 0$
 - (b) $(I - E)\Phi(u, \alpha) = 0$

where $E : Y \rightarrow \text{range} L$ is the projection associated to the splitting in 2(b).

***Reason:** This is primarily notational and requires no comment.
3. Use the equation 1(a) $X = \ker L \oplus M$: to write $u = v + w$, where $v \in \ker L$ and $w \in M$. Apply the implicit function theorem to solve $E\Phi(u, \alpha) = 0$ for w as a function of v and α . This leads to a function $W : \ker L \times R^{k+1} \rightarrow N$ such that $E\Phi(v + W(v, \alpha), \alpha) = 0$.

***Reason:** We want to show that the implicit function theorem is applicable. We extract a map $F : \ker L \times M \times R^{k+1} \rightarrow \text{range} L$ from 2(a); i.e., $F(v, w, \alpha) = E\Phi(v + w, \alpha)$. This differential of F with respect to w at the origin is $EL = L$. Now we argue that $L : M \rightarrow \text{range} L$ is invertible. (For simplicity, I don't want to say too much details in this notes.)
4. Define $\phi : \ker L \times R^{k+1} \rightarrow N$ by $\phi(v, \alpha) = (I - E)\Phi(v + W(v, \alpha), \alpha)$.

***Reason:** This is primarily notational and requires no comment.
5. Choose a basis v_1, v_2, \dots, v_n for $\ker L$ and a basis $v_1^*, v_2^*, \dots, v_n^*$ for $(\text{range} L)^\perp$. Define $g : R^n \times R^{k+1} \rightarrow R^n$ by $g_i(x, \alpha) = \langle v_i^*, \phi(x_1 v_1 + \dots + x_n v_n, \alpha) \rangle$.

***Reason:** In the writing $(\text{range} L)^\perp$ we are using (for the first time) the fact that Y is equipped with the inner product in the L^2 -sense (i.e. we write $\langle u, v \rangle = \int_\Omega u(x)v(x)dx$). Since L is Fredholm with index zero, $\dim \ker L = \dim(\text{range} L)^\perp$ and both dimensions are finite. Thus the bases for $\ker L$ and $(\text{range} L)^\perp$ contain the same number of vectors.

We summarize the outcome of the Liapunov-Schmidt reduction.

Proposition 5. *If the linearization of $\Phi(u, \alpha) = 0$ is a Fredholm operator of index zero, then solutions of this equations are (locally) in one-to-one correspondence with solutions of the finite system $g_i(x, \alpha) = 0$, $i = 1, 2, \dots, n$. where g_i is defined by $g_i(x, \alpha) = \langle v_i^*, \phi(x_1 v_1 + \dots + x_n v_n, \alpha) \rangle$.*