

On the inviscid limit problem for viscous incompressible flows in the half plane - Approach from vorticity formulation

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Abstract

The note is mainly for personal record, if you want to read it, please be careful. This Notes was taken when Prof. Yasunori Maekawa (Tohoku University, Japan) visiting Taiwan. I followed his lecture and took the note.

Overviews:

$$(NS) \begin{cases} \partial_t u + u \cdot \nabla u - \nu \Delta u + \nabla p = 0 & t > 0, x \in \mathbb{R}_+^2 \\ \nabla \cdot u = 0 & t \geq 0, x \in \mathbb{R}_+^2 \\ u = 0 & t \geq 0, x \in \partial\mathbb{R}_+^2 \\ u = a & t = 0, x \in \mathbb{R}_+^2 \end{cases}$$

where $\mathbb{R}_+^2 = \{(x_1, x_2) | x_2 > 0\}$, $u = (u_1, u_2)$: velocity, $a = (a_1, a_2)$: initial velocity, p : pressure and $\nu > 0$: kinematic viscosity (constant). $u = 0$ on $\partial\mathbb{R}_+^2$: no-slip B.C.. $\omega = \partial_1 u_2 - \partial_2 u_1 := \text{Rot}u$: vorticity. Note that $\text{Rot}\Delta u = \Delta \text{Rot}u$, $\text{Rot}(u, \nabla u) = u \cdot \nabla \text{Rot}u$ (since $\nabla \cdot u = 0$), $\text{Rot}(\nabla p) = 0$. Then these imply

$$\partial_t \omega + u \cdot \nabla \omega - \nu \Delta \omega = 0, t > 0, x \in \mathbb{R}_+^2.$$

- Vorticity is useful if there is no boundary (e.g. \mathbb{R}^2 , \mathbb{T}^2), which is well-studied.
- Behavior near the boundary? No-slip B.C. on u is a source of the vorticity on the boundary.
Basic question: B.C. on ω ? (vorticity formulation of (NS)): Topic 1.
For typical flows, ν is very small (for water 20°C, $\nu \sim 1.0 \times 10^{-6} \text{ m}^2/\text{s}$).

Problem: Behavior of $u = u^{(\nu)}$ in the limit $\nu \rightarrow 0$. Formally we obtain the Euler equation: For $u_E = (u_{E,1}, u_{E,2})$,

$$(E) \begin{cases} \partial_t u_E + u_E \cdot \nabla u_E + \nabla p_E = 0 & t > 0, x \in \mathbb{R}_+^2 \\ \nabla \cdot u_E = 0 & t \geq 0, x \in \mathbb{R}_+^2 \\ u_{E,2} = 0 & t \geq 0, x \in \partial\mathbb{R}_+^2 \\ u_E = a & t = 0, x \in \mathbb{R}_+^2 \end{cases}.$$

In general, $u_{E,1} \neq 0$ on $\partial\mathbb{R}_+^2$, while $u^{(\nu)} = 0$ and $a = 0$ on $\partial\mathbb{R}_+^2$.
 \Rightarrow Boundary layer appears.

Formal estimate of the boundary layer thickness δ (Parndtl 1904).
 $\partial_t u_1 + u \cdot \nabla u_1 - \nu \Delta u_1 + \partial_1 p = 0$, $\partial_1 u_1 + \partial_2 u_2 = 0$. Near the boundary, we expect
 $u_1, \partial_1 u_1, \partial_1^2 u_1, \partial_t u_1 \sim O(1)$, $\partial u_2 \sim O(\frac{1}{\delta})$, $\partial_2^2 u_1 \sim O(\frac{1}{\delta^2})$, $\partial_1 p \sim O(1)$. From
 $\nabla \cdot u = 0$, we have $\partial_2 u_2 \sim O(1) \Rightarrow u_2 \sim O(\delta)$, $u_2 \partial_2 u_1 \sim O(\delta) \cdot O(\frac{1}{\delta}) = O(1)$,
 $u_1 \partial_1 u_1 \sim O(1) \Rightarrow \frac{\nu}{\delta^2} \sim O(1)$, $\therefore \delta = \nu^{1/2}$.

Near the boundary $u^{(\nu)} \sim u_p^{(\nu)} = (v_{p,1}(t, x_1, \frac{x_2}{\nu^{1/2}}), u_{p,2}(t, x_1, \frac{x_2}{\nu^{1/2}}))$, $x = (x_1, X_2)$ where $X_2 = \frac{x_2}{\nu^{1/2}}$.

$$(P) \begin{cases} \partial_t v_{p,1} - \partial_{X_2}^2 v_{p,1} + v_p \cdot \nabla_x v_{p,1} + \partial_1 \pi_p = 0, & t > 0, x \in \mathbb{R}_+^2 \\ \nabla_x \cdot v_p = 0, \partial_{X_2} \pi_p = 0, v_p|_{t=0} = 0 \\ v_p|_{X_2=0} = 0, \lim_{X_2 \rightarrow 0} v_{p,1} = u_{E,1}|_{x_2=0}, \lim_{X_2 \rightarrow \infty} \pi_p = p_E|_{x_2=0} \end{cases} .$$

We want to justify $u^{(\nu)} \sim \begin{cases} u_E, & \frac{x_2}{\nu^{1/2}} \gg 1 \\ u_p^{(\nu)}, & \frac{x_2}{\nu^{1/2}} \ll 1 \end{cases}$ at least locally in time. Sammartino-

Caffisch (CMP, 98): Given data (initial velocity) a is analytic. This result is not applicable for, e.g., $a \in C_{0,\sigma}^\infty(\mathbb{R}_+^2)$.

Now, we justify $u^{(\nu)} \sim \begin{cases} u_E, & \frac{x_2}{\nu^{1/2}} \gg 1 \\ u_p^{(\nu)}, & \frac{x_2}{\nu^{1/2}} \ll 1 \end{cases}$ when the initial vorticity $b = \text{Rot} a$

satisfies $\text{dist}(\partial \mathbb{R}_+^2, \text{supp} b) > 0$ and Sobolev regularity: Topic 2.

1 Vorticity formulation for NS equation in \mathbb{R}_+^2

1.1 Derivation

Vorticity field $\omega = \partial_1 u_2 - \partial_2 u_1$ and $\nabla \cdot u = 0$ imply $-\Delta u = \nabla^\perp \omega$, where $\nabla^\perp = (\partial_2, -\partial_1)$. Biot-Savart law gives $u = \nabla^\perp (-\Delta_D)^{-1} \omega$, where $h = (-\Delta_D)^{-1} f$

is the solution of $\begin{cases} -\Delta h = f & \text{in } \mathbb{R}_+^2 \\ h = 0 & \text{on } \partial \mathbb{R}_+^2 \end{cases}$, Note that $\nabla \cdot \nabla^\perp (-\Delta_D)^{-1} \omega = 0$,

$\text{Rot} \nabla^\perp (-\Delta_D)^{-1} \omega = \omega$, $\gamma_{\partial \mathbb{R}_+^2} \partial_1 (-\Delta_D)^{-1} \omega = 0$ (trace).

(Derivation of vorticity B.C.)

Requirement: $\gamma_{\partial \mathbb{R}_+^2} \partial_2 (-\Delta_D)^{-1} \omega = 0$.

In \mathbb{R}_+^2 , ω satisfies $\partial_t \omega + u \cdot \nabla \omega - \nu \Delta \omega = 0$ in \mathbb{R}_+^2 , therefore,

$$\begin{aligned} 0 &= \partial_t \gamma_{\partial \mathbb{R}_+^2} \partial_2 (-\Delta_D)^{-1} \omega \\ &= \gamma_{\partial \mathbb{R}_+^2} \partial_2 (-\Delta_D)^{-1} \partial_t \omega \\ &= \gamma_{\partial \mathbb{R}_+^2} \partial_2 (-\Delta_D)^{-1} (\nu \Delta \omega - u \cdot \nabla \omega) \\ &= \gamma_{\partial \mathbb{R}_+^2} \partial_2 (-\Delta_D)^{-1} (\nu \Delta (\omega - \omega_{har}) - u \cdot \nabla \omega) \\ &= -\nu \gamma_{\partial \mathbb{R}_+^2} (\omega - \omega_{har}) - \gamma_{\partial \mathbb{R}_+^2} \partial_2 (-\Delta_D)^{-1} (u \cdot \nabla \omega) \\ &= -\nu \gamma_{\partial \mathbb{R}_+^2} \partial_2 \omega - \nu (-\partial_1^2)^{1/2} \gamma_{\partial \mathbb{R}_+^2} \omega - \gamma_{\partial \mathbb{R}_+^2} \partial_2 (-\Delta_D)^{-1} (u \cdot \nabla \omega) \end{aligned}$$

where ω_{har} satisfies $\begin{cases} \Delta\omega_{har} = 0 & \text{in } \mathbb{R}_+^2 \\ \omega_{har} = \omega & \text{on } \partial\mathbb{R}_+^2 \end{cases}$ and the last equation comes from

the Dirichlet-to-Neumann map on the half-plane property. $\therefore \nu(\partial_2\omega + (-\partial_1^2)^{1/2}\omega) = -\partial(-\Delta_D)^{-1}(u \cdot \nabla\omega)$ on $\partial\mathbb{R}_+^2$.

$$(V) \begin{cases} \partial_t\omega + M(\omega, \omega) - \nu\Delta\omega = 0 & t > 0, x \in \mathbb{R}_+^2 \\ \nu(\partial_2\omega + (-\partial_1^2)^{1/2}\omega) = N(\omega, \omega) & t > 0, x \in \partial\mathbb{R}_+^2 \\ \omega = \text{Rota} & t = 0, x \in \mathbb{R}_+^2 \end{cases}$$

where $M(f, g) = J(f) \cdot \nabla g$, $J(f) = \nabla^\perp(-\Delta_D)^{-1}f$, $N(f, g) = -\gamma_{\partial\mathbb{R}_+^2} J_1(M(f, g))$. Then (NS) \Leftrightarrow (V) + $\gamma_{\partial\mathbb{R}_+^2} a = 0$ (Note that we have used the fractional Laplacian, so the nonlocal property automatically holds).

1.2 Solution formula for linearization

$$(LV) \begin{cases} \partial_t\omega - \nu\Delta\omega = f & t > 0, x \in \mathbb{R}_+^2 \\ \nu(\partial_2\omega + (-\partial_1^2)^{1/2}\omega) = g & t > 0, x \in \partial\mathbb{R}_+^2 \\ \omega = b & y = 0, x \in \mathbb{R}_+^2 \end{cases}$$

and we have $(-\partial_1^2)^{1/2}\omega(\xi) = |\xi_1|\widehat{\omega}(\xi, \cdot)$ and $b = 0$ for simplicity, where $\widehat{\omega}(s, \xi_1, x_2) = \frac{1}{(2\pi)^{1/2}} \int_0^\infty \int_{\mathbb{R}} \omega(t, x) e^{-ix_1\xi_1 - ts} dx_1 dt$. Then we have

$$\begin{cases} \partial_2^2\widetilde{\omega} - (\frac{s}{\nu} + \xi^2)\widetilde{\omega} = -\frac{1}{\nu}\widetilde{f} & x_2 > 0 \\ \partial_2\widetilde{\omega} + |\xi_1|\widetilde{\omega} = \frac{\widetilde{g}}{\nu} & x_2 = 0, \widetilde{\omega} \rightarrow 0 (x_2 \rightarrow \infty). \end{cases}$$

$G(t, x) = \frac{1}{4\pi t} e^{-|x|^2/4t}$, $E(x) = -\frac{1}{2\pi} \log|x|$, $(h_1 \star h_2)$ is the standard convolution, and $(h_1 \star h_2) = \int_{\mathbb{R}_+^2} h_x(x - y^*) h_2(y) dy$, where $y^* = (y_1, -y_2)$. $h \star (gH_{\partial\mathbb{R}_+^2}^1)(x) = \int_{\mathbb{R}} h(x_1 - y_1, x_2) g(y_1) dy_1$, $\Gamma(t, x) = 2(\partial_1^2 + (-\partial_1^2)^{1/2}\partial_2)(E \star G(t))(x)$, $e^{t\Delta_N} f = G(t) \star f + G(t) \star f$, $\Gamma(0) \star f = \lim_{t \rightarrow 0} \Gamma(t) \star f = 2(\partial_1^2 + (-\partial_1^2)^{1/2}\partial_2)E \star f$.

Theorem 1.1. *The solution formula for (LV) is given by*

$$\begin{aligned} \omega(t) &= e^{\nu t B} b - \Gamma(0) \star b + \int_0^t e^{\nu(t-s)B} (f(s) - g(s)H_{\partial\mathbb{R}_+^2}^1) ds \\ &\quad - \int_0^t \Gamma(0) \star (f(s) - g(s)H_{\partial\mathbb{R}_+^2}^1) ds \end{aligned}$$

where $e^{\nu t B} := e^{\nu t \Delta_N} + \Gamma(\nu t) \star$.

Refer to ‘‘Solution formula for the Stokes equation: Solonnikov (AMS Transl 68, Ukai (CPAM 87)).’’

Proposition 1.2. *If $g = \gamma_{\partial\mathbb{R}_+^2} J_1(f) = \gamma_{\partial\mathbb{R}_+^2} \partial_2(-\Delta_D)^{-1}f$, then $\Gamma(0) \star (f - gH_{\partial\mathbb{R}_+^2}^1) = 0$ in \mathbb{R}_+^2 . In particular, if $\gamma_{\partial\mathbb{R}_+^2} J_1(b) = 0$, then $\Gamma(0) \star b = 0$ in \mathbb{R}_+^2 .*

(Note: $\nabla \cdot a = 0$, $b = \text{Rota}$, $\gamma_{\partial\mathbb{R}_+^2} a = 0 \Rightarrow \gamma_{\partial\mathbb{R}_+^2} J(b) = 0$.)

Proof. (Prop 1.2)

$$\begin{aligned}
E * (f - gH_{\partial\mathbb{R}_+^2}^1) &= \int_{\mathbb{R}_+^2} E(x - y^*)f(y)dy + \int_{\partial\mathbb{R}_+^2} E(x - y^*)\partial_{11}(-\Delta_D)^{-1}f d\nu_y^1 \\
&= \int_{\mathbb{R}_+^2} \nabla_y E(x - y^*) \cdot \nabla_y(-\Delta_D)^{-1}f dy \\
&= - \int_{\mathbb{R}_+^2} \Delta_y E(x - y^*)f(y)dy = 0
\end{aligned}$$

if $x \in \mathbb{R}_+^2$. □

Proposition 1.3. $\Gamma(\nu t) * b - \Gamma(0) * b = -\nu \int_0^t \mathfrak{S}G(\nu s)ds * b$ in \mathbb{R}_+^2 and $\mathfrak{S} = 2(\partial_1^2 + (-\partial_1^2)^{1/2}\partial_2)$.

Proof. RHS = $\int_0^t \mathfrak{S}(-\Delta_{\mathbb{R}^2})^{-1}\partial_\xi(G(\nu s))ds * b = \mathfrak{S}E * G(\nu t) * b - \mathfrak{S}E * b$. □

1.3 Properties of $\{e^{tB}\}_{t \geq 0}$

Set $\dot{W}_{0,\sigma}^{1,q}(\mathbb{R}_+^2) = \overline{C_{0,\sigma}^\infty(\mathbb{R}_+^2)}^{\|\nabla^a\|_{L^q}}$, $1 < q < \infty$. $X_q = \{\text{Rota} \in L^q(\mathbb{R}_+^2) | a \in \dot{W}_{0,\sigma}^{1,q}(\mathbb{R}_+^2)\}$.

Theorem 1.4. $\{e^{tB}\}_{t > 0}$ defines a C_0 -analytic semigroup in X_q . Moreover, its generator B_q is given by

$$D(B_q) = \{f \in X_q \cap W^{2,q}(\mathbb{R}_+^2) | \gamma_{\partial\mathbb{R}_+^2}(\partial_2 f + (-\partial_1^2)^{1/2}f) = 0\},$$

and $B_q f = \Delta f$ when $f \in D(B_q)$. Moreover, $\|\nabla^2 f\|_{L^q} \leq C\|B_q f\|_{L^q}$, $f \in D(B_q)$.

2 Inviscid limit problem

2.1 Result

$$(\text{NS}) \begin{cases} \partial_t u^{(\nu)} + u^{(\nu)} \cdot \nabla u^{(\nu)} - \nu \Delta u^{(\nu)} + \nabla p^{(\nu)} = 0 & t \in (0, T), x \in \mathbb{R}_+^2 \\ \nabla \cdot u = 0 & t \in (0, T), x \in \mathbb{R}_+^2 \\ u = 0 & t \in (0, T), x \in \partial\mathbb{R}_+^2 \\ u = a & t = 0, x \in \mathbb{R}_+^2 \end{cases}$$

v_p : velocity of the Prandtl flow, $\tilde{v}_p = (\tilde{v}_{p,1}, \tilde{v}_{p,2})$, $\tilde{v}_{p,1} = v_{p,1} - \gamma_{\partial\mathbb{R}_+^2} u_{E,1}$, $\tilde{v}_{p,2} = \int_{x_2}^\infty \partial_1 \tilde{v}_{p,1} dY_2$.

(Velocity of the modified Prandtl flow)

$$\tilde{u}_{p,1}^{(\nu)}(t, x) = \tilde{v}_{p,1}(t, x_1, \frac{x_2}{\nu^{1/2}}), \tilde{u}_{p,2}^{(\nu)}(t, x) = \nu^{1/2} \tilde{v}_{p,2}(t, x_1, \frac{x_2}{\nu^{1/2}}).$$

Theorem 2.1. (*M., to appear in CPAM*)

Let $a \in \dot{W}_{0,\sigma}^{1,p}(\mathbb{R}_+^2) \cap W^{4,2}(\mathbb{R}_+^2)$ for some $1 < p < 2$ and $b = \partial_1 a_2 - \partial_2 a_1 \in W^{4,1}(\mathbb{R}_+^2) \cap W^{4,2}(\mathbb{R}_+^2)$. Assume that $d_0 = \text{dist}(\partial\mathbb{R}_+^2, \text{supp} b) > 0$. Then $\exists T, C > 0$ such that

$$\sup_{0 < t < T} \|u^{(\nu)}(t) - u_E(t) - \tilde{u}_p^{(\nu)}(t)\|_{L^\infty} \leq C\nu^{1/2}$$

for sufficiently small $\nu > 0$. The time T is estimated from below as $T \geq c \min\{d_0, 1\}$ with $c > 0$ depending only on $\|b\|_{W^{4,1} \cap W^{4,2}}$.

(Away the boundary, (NS) is estimated by Euler equation;; Near the boundary, (NS) is estimated by Prandtl equation)

We assume $0 < d_0 \ll 1$, for simplicity.

Note: $\omega_E = \text{Rot} u_E \in C^1([0, T] \times \mathbb{R}_+^2) \cap L^\infty(0, T; W^{4,1} \cap W^{4,2}) \forall T > 0$ satisfies $\partial_t \omega_E + u_E \cdot \nabla \omega_E = 0$.

In particular, $\cup_{0 < t < T_0} \text{supp} \omega_E(t) \subset \{x \in \mathbb{R}_+^2 \mid x_2 \geq \frac{d_0}{2}\}$ for $T_0 = c_0 d_0$ with some $C_0 > 0$ depending only on $\|b\|_{W^{4,1} \cap W^{4,2}}$.

- Key observations for the proof of theorem 2.1:

(1) Analyticity of the data near the boundary (from the Prandtl) \Rightarrow Local solvability of the Prandtl equation (cf. Sammartino-Caflisch (CMP '98), Lombardo-Cannone-Sammartino (SIMA JMA '03), Kukavica-Vicol (CMS '13)).

(2) Exponential smallness in ν^{-1} of the vorticity in the region between the boundary layer and $\text{supp} \omega_E \Rightarrow$ Small direct interaction between the vorticity of the outer flow and the vorticity created on the boundary.

We make the ansatz $\omega^{(\nu)} = \omega_E + R_{\frac{1}{\nu}} \omega_p + R_{\frac{1}{\nu}} \omega_{IP}^{(\nu)} + \omega_{IE}^{(\nu)}$, the last two are remainder terms, $(R_{\frac{1}{\nu}} f)(t, x) = \frac{1}{\nu^{1/2}} f(t, x_2, \frac{x_2}{\nu^{1/2}})$.

$$(V_E) \begin{cases} \partial_t \omega_E + M(\omega_E, \omega_E) = 0 \\ \omega_E|_{t=0} = \text{Rota} \end{cases}$$

where $M(f, g) = J(f) \cdot \nabla g$, $J(f) = \nabla^\perp (-\Delta_D)^{-1} f$.

$$(V_P) \begin{cases} \partial_t \omega_p - \partial_{X_2}^2 \omega_p = -v_p \cdot \nabla_X \omega_p & t > 0, x \in \mathbb{R}_+^2 \\ \partial_t \omega_p = - \int_0^\infty v_p \cdot \nabla_X \omega_p dY_2 + N(\omega_E, \omega_E) & \text{on the boundary} \\ \omega_p|_{t=0} = 0 \end{cases}$$

2.2 Function spaces

- $\mu, \rho, \theta \geq 0$: parameters.
- ξ_1 : wave number in x_1 direction.
- $X_2 = \nu^{-1/2} x_2$.
- $(\alpha)_+ = \max(\alpha, 0)$, $\alpha \in \mathbb{R}$.

$$\begin{aligned} \varphi_{p,\nu}^{(\mu,\rho)} &= \exp\left(\frac{(\mu - \nu^{1/2} X_2)_+ |\xi_1|}{4} + \rho X_2^2\right), \\ \varphi_{E,\nu}^{(\mu,\rho)}(\xi_1, X_2) &= \exp\left(\frac{(\mu - x_2)_+ |\xi_1|}{4} + \frac{\theta}{\nu} \left(\frac{d_0}{8} - x_2\right)_+^2\right), \\ \hat{f}(\xi_1, x_2) &= \mathcal{F}_{x_1 \rightarrow \xi_1} [f(\cdot, x_2)](\xi_1), \|\hat{f}\|_{L_{\xi_1}^p L_{x_2}^q} = \left(\int_{\mathbb{R}} \left(\int_0^\infty |\hat{f}(\xi_1, x_2)|^q dx_2\right)^{p/q} d\xi_1\right)^{1/p}, \\ \|f\|_{X_{IP\nu,0}^{(\mu,\rho)}} &= \sum_{k=0,1} \|\varphi_{p,\nu}^{(\mu,\rho)} X_2^{k/2} \hat{f}\|_{L_{\xi_1}^2 L_{x_2}^{1+k}}, \|f\|_{X_{IP\nu,j}^{(\mu,\rho)}}, j = 1, 2: \text{additional Sobolev} \\ &\text{regularity. } \|f\|_{X_{p,2}^{(\mu,\rho)}} := \|f\|_{X_{IP_0,2}^{(\mu,\rho)}} (\nu = 0), \|f\|_{X_{IE\nu,0}^{(\mu,\theta)}} = \|\varphi_{E,\nu}^{(\mu,\theta)} \hat{f}\|_{L_{\xi_1}^2, L_{x_2}^2} + \\ &\|\varphi_{E,\nu}^{(0,\theta)} f\|_{L_x^1}, \|f\|_{X_{IE\nu,j}^{(\mu,\theta)}}, j = 1, 2: \text{additional Sobolev regularity.} \end{aligned}$$

Theorem 2.2. $\exists C, T, \mu, \rho, \theta > 0$ such that

$$\sup_{0 < t < T} \|\omega_p(t)\|_{X_p^{(\mu, \frac{\rho}{t})}} \leq C,$$

$$\sup_{0 < t < T} (\|\omega_{IP}^{(\nu)}(t)\|_{X_{IP, \nu, 1}^{(\mu, \frac{\rho}{t})}} + \|\omega_{IE}^{(\nu)}(t)\|_{X_{IE, \nu, 1}^{(\mu, \frac{\rho}{t})}}) \leq C\nu^{1/2}.$$

$$u^{(\nu)} = J(\omega^{(\nu)}).$$

2.3 Biot-Savart law

Lemma 2.3. *We have*

$$\begin{aligned} \mathcal{F}(\partial_1(-\Delta_D)^{-1}f)(\xi_1, x_2) &= \frac{1}{2} \frac{i\xi_1}{|\xi_1|} \left\{ \int_0^\infty e^{-|\xi_1|(x_2-z_2)} (1 - e^{-2|\xi_1|z_2}) \hat{f}(\xi_1, z_2) dz_2 \right. \\ &\quad \left. + \int_0^\infty e^{-|\xi_1|(z_2-x_2)} (1 - e^{-2|\xi_1|x_2}) \hat{f}(\xi_1, z_2) dz_2 \right\}, \end{aligned}$$

$$\begin{aligned} \mathcal{F}(\partial_2(-\Delta_D)^{-1}f)(\xi_1, x_2) &= \frac{1}{2} \left\{ - \int_0^{x_2} e^{-|\xi_1|(x_2-z_2)} (1 - e^{-2|\xi_1|z_2}) \hat{f}(\xi_1, z_2) dz_2 \right. \\ &\quad \left. + \int_{x_2}^\infty e^{-|\xi_1|(z_2-x_2)} (1 + e^{-2|\xi_1|x_2}) \hat{f}(\xi_1, z_2) dz_2 \right\}. \end{aligned}$$

Note: If $\text{supp } f \subset \{x \in \mathbb{R}^2 | x_2 \geq m > 0\}$, then for $x_2 < m$, we have

$$\begin{aligned} |\mathcal{F}[\partial_j(-\Delta_d)^{-1}f](\xi_1, x_2)| &\leq c \int_m^\infty e^{-|\xi_1|(z_2-x_2)} |\hat{f}(\xi_1, z_2)| dz_2 \\ &\leq e^{-|\xi_1|(m-x_2)} \int_0^\infty |\hat{f}(\xi_1, z_2)| dz_2. \end{aligned}$$

- Key ingredient of the proof:
 - (1) Solution formula for linearized (vorticity) problem. Weighted norm estimates for linear and bilinear maps.
 - (2) Pointwise estimate for the Green function of $\partial_t - \nu\Delta + u \cdot \nabla$ under the Neumann boundary condition.
 - (3) Abstract Cauchy-Kowalevsky theorem.
- Key propositions

Proposition 2.4. *Let $0 < s < t$, $\mu > 0$, $0 < \rho, \theta \ll 1$. Then*

$$\begin{aligned} \|R_\nu e^{\nu(t-s)\Delta_N} R_{\frac{1}{\nu}} f\|_{X_{IP, \nu, 0}^{(\mu, \frac{\rho}{t})}} &\lesssim \|f\|_{X_{IP, \nu, 0}^{(\mu, \frac{\rho}{s})}}, \\ \|e^{\nu(t-s)\Delta_N} f\|_{X_{IE, \nu, 0}^{(\mu, \frac{\rho}{t})}} &\lesssim \|f\|_{X_{IE, \nu, 0}^{(\mu, \frac{\rho}{s})}}. \end{aligned}$$

Proof. Set $g(t, X_2) = \frac{1}{(4\pi t)^{1/2}} e^{-x_2^2/4t}$, $g_N(t, X_2, Y_2) = g(t, X_2 - Y_2) + g(t, X_2 + Y_2)$. Then

$$\begin{aligned} \mathcal{F}[R_\nu e^{\nu(t-s)\Delta_N} R_{\frac{1}{\nu}} f](\xi_1, X_2) &= e^{-\nu(t-s)\xi_1^2} \int_0^\infty g_N(t-s, X_2, Y_2) \hat{f}(\xi_1, Y_2) dY_2 \\ &= e^{-\nu(t-s)\xi_1^2} \int_0^\infty g_N(t-s, X_2, Y_2) e^{-\frac{1}{4}(\mu-\nu^{1/2}Y_2)_+} \\ &\quad \times e^{|\xi_1|} \varphi_{p, \nu}^{(\mu, 0)} \hat{f} dY_2. \end{aligned}$$

Therefore,

$$|\varphi_{p,\nu}^{(\mu,\frac{p}{t})} \mathcal{F}[R_\nu e^{\nu(t-s)\Delta_N} R_{\frac{1}{\nu}} f](\xi_1, X_2) \lesssim \frac{e^{\frac{p}{t} X_2^2}}{(t-s)^{1/2}} \int_0^\infty e^{-\nu(t-s)\xi_1^2 - \frac{|X_2 - Y_2|^2}{4(t-s)}} \\ \times e^{\frac{(\mu - \nu^{1/2} X_2)_+ - (\mu - \nu^{1/2} Y_2)_+}{4}} |\xi_1| |\varphi_{p,\nu}^{(\mu,0)} \hat{f}| dY_2.$$

By

$$\begin{aligned} (\mu - \nu^{1/2} X_2)_+ |\xi_1| &\leq (\mu - \nu^{1/2} Y_2)_+ |\xi_1| + \nu^{1/2} |X_2 - Y_2| |\xi_1| \\ &\leq (\mu - \nu^{1/2} Y_2)_+ |\xi_1| + \nu(t-s)\xi_1^2 + \frac{|X_2 - Y_2|^2}{4(t-s)} \\ &\lesssim \frac{e^{\frac{p}{t} X_2^2}}{(t-s)^{1/2}} \int_0^\infty e^{-\frac{3}{4}\nu(t-s)\xi_1^2} e^{-\frac{|X_2 - Y_2|^2}{8(t-s)}} |\varphi_{p,\nu} \hat{f}| dY_2, \end{aligned}$$

∴ Young-type inequality with weights gives

$$\|\varphi_{p,\nu}^{(\mu,\frac{p}{t})} \mathcal{F}[R_\nu e^{\nu(t-s)\Delta_N} R_{\frac{1}{\nu}} f]\|_{L_{X_2}^1} \lesssim \|\varphi_{p,\nu}^{(\nu,\frac{p}{s})} \hat{f}(\xi_1)\|_{L_{X_2}^1}$$

and

$$\|\varphi_{p,\nu}^{(\mu,\frac{p}{t})} \mathcal{F}[R_\nu e^{\nu(t-s)\Delta_N} R_{\frac{1}{\nu}} f]\|_{L_{\xi_1}^2 L_{X_2}^1} \lesssim \|\varphi_{p,\nu}^{(\nu,\frac{p}{s})} \hat{f}(\xi_1)\|_{L_{\xi_1}^2 L_{X_2}^1}.$$

□

$\omega^{(\nu)} = \omega_E + R_{\frac{1}{\nu}} \omega_p + R_{\frac{1}{\nu}} \omega_{IP}^{(\nu)} + \omega_{IE}^{(\nu)}$, the last term is the remainder of the outer flow.

$$(V_{IE\nu}) \begin{cases} \partial_t \omega_{IE} - \nu \Delta \omega_{IE} + M(\omega^{(\nu)}, \omega_{IE}) = H^{(\nu)} \\ \partial_2 \omega_{IE} = 0 \\ \omega_{IE}|_{t=0} = 0 \end{cases} \quad \text{on the boundary}$$

and $M(\omega^{(\nu)}, \omega_{IE}) = u^{(\nu)} \cdot \nabla \omega_{IE}$, $\nu(\partial_2 \omega^{(\nu)} + (-\partial_1^2)^{1/2} \omega^{(\nu)}) = \text{Nonlinear} \Rightarrow \partial_2 \omega_{IE} = 0$.

$$\begin{aligned} H^{(\nu)} &= -M(R_{\frac{1}{\nu}} \omega_{IP}^{(\nu)} + \omega_{IE}^{(\nu)}, \omega_E) + \nu \Delta \omega_E \\ &= -J(R_{\frac{1}{\nu}} \omega_{IP}^{(\nu)} + \omega_{IE}^{(\nu)}) \cdot \nabla \omega_E + \nu \Delta \omega_E, \end{aligned}$$

∴ $\cup_{0 < t < T} \text{supp} H^{(\nu)}(t) \subset \{x \in \mathbb{R}^2 | x_2 \geq \frac{d_0}{2}\}$.

Proposition 2.5. $\omega_{IE}^{(\nu)} = \int_0^t \int_{\mathbb{R}_+^2} P_u^{(\nu)}(t, x; s, y) H^{(\nu)}(s, y) dy ds$, $0 < P_u^{(\nu)}(t, x; s, y) \leq \frac{1}{2\pi\nu(t-s)} \exp\left(-\frac{(|x-y| - \int_s^t \|u^{(\nu)}(t)\|_{L^\infty})_+^2}{4\nu(t-s)}\right)$.

(From Carlen-Loss '95 Duke)

Exponential decay in ν^{-1} of ω_{IE} near boundary is observed as follows:

$$|\omega_{IE}^{(\nu)}(t, x)| \lesssim \int_0^t \int_{\frac{d_0}{2}}^\infty \frac{1}{\nu(t-s)} \exp\left(-\frac{(|x-y| - \int_s^t \|u^{(\nu)}(t)\|_{L^\infty})_+^2}{4\nu(t-s)}\right) \\ \times |H^{(\nu)}| dy ds.$$

\therefore If $x_2 \leq \frac{d_0}{4}$ and $0 < t < T = O(d_0) \ll 1$, $\sup_{0 < t < T} \|u^{(\nu)}(t)\|_{L^\infty} \leq C$, then

$$|\omega_{IE}(t, x)| \lesssim d_0^{-2} e^{-\frac{d_0^2}{8\nu t}} \int_0^t \|H^{(\nu)}\|_{L^1} ds.$$

For the third part, Cauchy-Kowalevsky theorem. (Nirenberg '72, Nishida '77 ...)