

MONOTONICITY-BASED INVERSION OF FRACTIONAL SEMILINEAR ELLIPTIC EQUATIONS WITH POWER TYPE NONLINEARITIES

YI-HSUAN LIN

ABSTRACT. We investigate the monotonicity method for fractional semilinear elliptic equations with power type nonlinearities. We prove that if-and-only-if monotonicity relations between coefficients and the derivative of the Dirichlet-to-Neumann map hold. Based on the strong monotonicity relations, we study a constructive global uniqueness for coefficients and inclusion detection for the fractional Calderón type inverse problem. Meanwhile, we can also derive the Lipschitz stability with finitely many measurements. The results hold for any $n \geq 1$.

Keywords. Calderón problem, fractional Laplacian, nonlocal, L^p -estimates, semilinear elliptic equations, monotonicity, Runge approximation, localized potentials, Lipschitz stability.

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1. INTRODUCTION

In this work, we extend the monotonicity method [HL19, HL20] to the case of fractional semilinear elliptic equations with power type nonlinearities. The mathematical formulation is given as follows. Let $\Omega \subset \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ -boundary $\partial\Omega$, for $n \geq 1$. For $0 < s < 1$, and any $m \geq 2$, $m \in \mathbb{N}$. Let $q \in L^\infty(\Omega)$ be a potential, then we consider the Dirichlet problem for the fractional semilinear elliptic equation with power type nonlinearities

$$(1.1) \quad \begin{cases} (-\Delta)^s u + qu^m = 0 & \text{in } \Omega, \\ u = f & \text{in } \Omega_e := \mathbb{R}^n \setminus \bar{\Omega}. \end{cases}$$

The well-posedness of (1.1) holds for any sufficiently small exterior data f in an appropriate function space, which will be demonstrated in Section 2. Here the fractional Laplacian $(-\Delta)^s$ is defined via the integral representation

$$(1.2) \quad (-\Delta)^s u = c_{n,s} \text{P.V.} \int_{\mathbb{R}^n} \frac{u(x) - u(y)}{|x - y|^{n+2s}} dy,$$

for $u \in H^s(\mathbb{R}^n)$, where P.V. denotes the principal value and

$$(1.3) \quad c_{n,s} = \frac{\Gamma(\frac{n}{2} + s)}{|\Gamma(-s)|} \frac{4^s}{\pi^{n/2}}$$

is a constant that was explicitly calculated in [DNPV12]. Here $H^s(\mathbb{R}^n)$ is the fractional Sobolev space, which will be introduced in Section 2. On one hand, we want to emphasize that the regularity condition of $\partial\Omega \in C^{1,1}$ is needed due to the well-posedness and suitable L^p -estimates for the fractional Laplacian. On the other hand, it is worth mentioning that in the study of fractional inverse problems for linear equations, in general we do not need regularity assumption on the domain.

In this article, we study the fractional type Calderón problem for the equation (1.1) of reconstruction an unknown potential q from the (exterior) *Dirichlet-to-Neumann* (DN) map Λ_q :

$$\Lambda_q : H^s(\Omega_e) \rightarrow H^s(\Omega_e)^*, \quad f \mapsto (-\Delta)^s u|_{\Omega_e},$$

for any sufficiently small exterior data $f \in H^s(\Omega_e)$, where $u \in H^s(\mathbb{R}^n)$ is the solution of (1.1) and $H^s(\Omega_e)^*$ is the dual space of $H^s(\Omega_e)$. For the sake of self-containedness, we will provide the proof of the well-posedness of (1.1) under the smallness condition of exterior data, which implies that the DN map Λ_q of (1.1) is well-defined in the exterior domain Ω_e . The fractional Calderón problem was first proposed by Ghosh-Salo-Uhlmann [GSU20], and related fractional inverse problems have been investigated by many researchers recently, such as [CLL19, CLR20, GLX17, GRSU20, HL19, HL20, LL20, LL19, RS20, LLR20] and the references therein. The key ingredients in the fractional inverse problems are the *strong uniqueness* (Proposition 3.3) and the *Runge approximation* (Theorem 3.2) in $L^p(\Omega)$, for $p > 1$. Based on these properties, many researchers have developed the fractional Calderón problem with partial data, monotonicity-based inversion formula and simultaneously recovering problems.

The research of fractional semilinear Schrödinger equations arises in the quantum effects in Bose-Einstein Condensation [UB13]. In the ideal boson systems, the Gross-Pitaevskii equations characterizes condensation of weakly interacting boson atoms at a low temperature, wherever the probability density of quantum particles is conserved. Moreover, in the inhomogeneous media with long-range or nonlocal interactions between particles, this yields the density profile no longer retains its shape as in the classical Gross-Pitaevskii equations. This dynamics can be described by the fractional Gross-Pitaevskii equation, regarded as the fractional semilinear Schrödinger equation, in which the turbulence and decoherence emerge. It was investigates in [KZ16] that the turbulence appears from the nonlocal property of the fractional Laplacian; while the local nonlinearity helps maintain coherence of the density profile.

In general, it is known that the nonlinear and nonlocal problems are harder than their local counterparts for forward mathematical problems. For the local case, i.e., $s = 1$, one can consider the analogous inverse boundary value problem for the semilinear elliptic equation $\Delta u + a(x, u) = 0$ in Ω with $u = f$ on $\partial\Omega$. Similar inverse problems are recently treated in the independent works [FO19, LLLS20a]. By using the knowledge of the corresponding DN map, the authors [FO19, LLLS20a]

have introduced the *higher order linearization* method, to investigate that the unknown coefficients can be uniquely determined by its associated DN map (on the boundary). In addition, [LLS20b, KU20, KU19] have extended the unique determination results into the partial data setup, and the key ingredient is also relied on the higher order linearization. More specifically, the *first* linearization will make the unknown coefficients disappear, so that one can apply the *density* property of the scalar products of *harmonic functions* (see [Cal80, FKSU09]). For general linear elliptic equations, one needs more complicated results to prove the density property of the scalar products of solutions to the certain equation, which might involve the *complex geometrical optics* solutions.

Very recently, Lai and myself [LL20] have studied related inverse problems for fractional semilinear elliptic equations. We can recover the unknown coefficients and obstacles by using the higher order linearization, where we have simply used a single parameter ϵ . In fact, we only need to utilize a single exterior measurement to recover coefficient and obstacle simultaneously. The goal of this work is to study related fractional inverse problems for (1.1) via the *monotonicity tests*.

Let us formulate the *if-and-only-if* monotonicity relations in the following. For any potentials $q_1, q_2 \in L^\infty(\Omega)$, we will use the monotonicity arguments and localized potentials for the linearized equations to show that

$$(1.4) \quad q_1 \leq q_2 \quad \text{if and only if} \quad (D^m \Lambda_{q_1})_0 \leq (D^m \Lambda_{q_2})_0,$$

where $m \in \mathbb{N}$ is the integer of the fractional elliptic equation (1.1) with power type nonlinearities $q_j(x)u^m$, for $j = 1, 2$. Here $q_1 \leq q_2$ means that $q_1(x) \leq q_2(x)$ for almost everywhere (a.e.) $x \in \Omega$.

In this work, the inequality $(D^m \Lambda_{q_1})_0 \leq (D^m \Lambda_{q_2})_0$ in (1.4) is denoted in the sense that

$$(1.5) \quad \underbrace{\langle (D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0 \rangle}_{m\text{-linear form}}(g, \dots, g), \underbrace{h}_{m\text{-vector}} \leq 0,$$

for any $g \in C_c^\infty(\Omega_e)$ and for some suitable $h \in C_c^\infty(\Omega_e)$. The exterior data $h \in C_c^\infty(\Omega_e)$ would be chosen differently when the integer number m is even or m is odd. We will give more detailed discussions in Section 3. Here $(D^m \Lambda_q)_0$ denotes the m -th order derivative of the DN map Λ_q evaluated at the 0 exterior data, and it can be computed directly from

$$(D^m \Lambda_q)_0(g, \dots, g)|_{\Omega_e} = \partial_\epsilon^m|_{\epsilon=0} (-\Delta)^s u_{\epsilon g}|_{\Omega_e},$$

where $u_{\epsilon g} \in H^s(\mathbb{R}^n)$ is the solution of

$$(-\Delta)^s u + qu^m = 0 \text{ in } \Omega \quad \text{with} \quad u = \epsilon g \text{ in } \Omega_e.$$

We will characterize the preceding discussions in Section 2 with more details. In addition, once we know the information of exterior measurements Λ_q , then we can determine the m -th order derivative of Λ_q .

The first main result in this work is that the if-and-only-if monotonicity relations (1.4) yield a constructive uniqueness proof of the potential $q(x)$ by knowing the knowledge of the m -th order derivative of the DN map Λ_q . The first main result in this paper is stated as follows.

Theorem 1.1 (The if-and-only-if monotonicity relations). *Consider $\Omega \subset \mathbb{R}^n$, $n \geq 1$ to be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $q_1, q_2 \in L^\infty(\Omega)$, $m \geq 2$ and $m \in \mathbb{N}$. Let Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. Then we have*

$$(1.6) \quad q_1 \geq q_2 \text{ a.e. in } \Omega \quad \text{if and only if} \quad (D_0^m \Lambda_{q_1})_0 \geq (D^m \Lambda_{q_2})_0.$$

Remark 1.1. *It is worth mentioning that*

- (a) When $s = 1$, i.e., for the local case, one can only expect that the monotonicity relations of potentials will imply the monotonicity relations of the corresponding DN maps. It is hard to show a converse statement to be true of the monotonicity formula. Fortunately, with the aids of the strong uniqueness of the fractional Laplacian, we are able to prove Theorem 1.1 (see Section 4), which is similar to the works [HL19, HL20].
- (b) It is natural to consider the m -th order derivative of DN map $(D^m \Lambda_q)_0$ instead of the original DN map Λ_q . Due to the well-posedness, one can trace the information of $(D^k \Lambda_q)_0$ for all $k \in \mathbb{N}$, and one cannot see any differences of $(D^k \Lambda_q)_0$ for any $k = 0, 1, \dots, m-1$ (see Section 2).

The proof of Theorem 1.1 is based on the monotonicity formulas and the localized potentials for the fractional Laplacian (see Section 3 and Section 4). Thanks to the strong uniqueness for the fractional Laplacian, one can approximate any L^a function by solutions of the fractional Laplacian, for any $a > 1$. Then one can construct the localized potentials for the fractional Laplacian by using the standard normalization technique.

In the study of inverse boundary value problem, the technique of combining monotonicity relations with localized potentials [Geb08] is a useful approach, and this method has already been studied extensively in a number of results, such as [AH13, BHHM17, BHKS18, GH18, Har09, Har12, HL19, HLL18, HPS19a, HPS19b, HS10, HU13, HU17, SKJ⁺19]. Also, several works have built practical reconstruction based on monotonicity properties [DFS20, Gar17, Gar19, GS17, GS19, HLU15, HM16, HM18, HU15, MVVT16, SUG⁺17, TR02, TSV⁺16, VMC⁺17, ZHS18].

The second main result is that we investigate the inverse obstacle problem for the exterior problem (1.1) of determining regions where a potential $q \in L^\infty(\Omega)$ changes from a known potential $q_0 \in L^\infty(\Omega)$. Our goal is not only to show the unique determination the unknown obstacle from the exterior measurements, but also we will give a reconstruction formula of the support $q - q_0$ by comparing $(D^m \Lambda_q)_0$ with $(D^m \Lambda_{q_0})_0$. The potential q_0 is denoted as a background coefficient, and q denotes the coefficient function in the presence of anomalies or scatterers.

In the spirit of [Gar17, HU13, HL19, HL20], we will show that the support of $q - q_0$ can be reconstructed via the monotonicity tests. Let $M \subset \Omega$ be a measurable set, and we define the testing operator $T_M : H^s(\Omega_e)^m \rightarrow H^s(\Omega)^*$ via the pairing that

$$(1.7) \quad \langle (T_M)(g, \dots, g), h \rangle := \int_{\Omega_e} (T_M)(g, \dots, g) h \, dx = \int_M v_g^m v_h \, dx,$$

where T_M is regarded as an m -form acting on m -vector valued functions. Here v_g and v_h are the solution of the fractional Laplacian in Ω with $v_g = g$ and $v_h = h$ in Ω_e , respectively. Notice that the testing operator (1.7) can be computed since we know the location of the measurable set $M \subset \Omega$ and the information of v_g, v_h once $g, h \in C_c^\infty(\Omega_e)$ are given in the exterior domain Ω_e .

The following theorem shows that the support of $q - q_0$ can be found by shrinking closed set. We also refer readers to [HU13, GS19, HL19, HL20] for the linear cases.

Theorem 1.2 (Unknown inclusion detection). *Consider $\Omega \subset \mathbb{R}^n$, $n \geq 1$ to be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $q_1, q_2 \in L^\infty(\Omega)$, $m \geq 2$ and $m \in \mathbb{N}$. Let Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. For each closed subset $C \subseteq \Omega$,*

$$\begin{aligned} \text{supp}(q - q_0) &\subseteq C, \\ \text{if and only if } \exists \alpha > 0 : & -\alpha T_C \leq (D^m \Lambda_q)_0 - (D^m \Lambda_{q_0})_0 \leq \alpha T_C. \end{aligned}$$

Thus,

$$\begin{aligned} & \text{supp}(q - q_0) \\ &= \bigcap \{C \subseteq \Omega \text{ closed} : \exists \alpha > 0 : -\alpha T_C \leq (D^m \Lambda_q)_0 - (D^m \Lambda_{q_0})_0 \leq \alpha T_C\}. \end{aligned}$$

Note that Theorem 1.2 is not a deterministic result, but it is a reconstruction result. The proof of Theorem 1.2 can be regarded as an application of Theorem 1.1. Via the monotonicity tests, we can give a reconstruction algorithm by utilizing the testing operator T_M in Section 4.

The last main contribution of this article is about the *Lipschitz stability* of the fractional inverse problem with finitely many measurements. The Lipschitz stability with finitely many measurements has been studied by in various mathematical settings, we refer the reader to [HM19, HL20, Sin07, RS19] and references therein for more detailed descriptions. In this work, we only consider the case that the set $\mathcal{Q} \subset L^\infty(\Omega)$ is a finite-dimensional subspace of piecewise analytic functions, and

$$\mathcal{Q}_\lambda := \{q \in \mathcal{Q} : \|q\|_{L^\infty(\Omega)} \leq \lambda\},$$

for some constant $\lambda > 0$.

Theorem 1.3. *Consider $\Omega \subset \mathbb{R}^n$, $n \geq 1$ to be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $q_1, q_2 \in L^\infty(\Omega)$, $m \geq 2$ and $m \in \mathbb{N}$. Let Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. Then there exists a constant $c_0 > 0$ such that*

$$(1.8) \quad \|(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0\|_* \geq c_0 \|q_1 - q_2\|_{L^\infty(\Omega)},$$

for any $q_1, q_2 \in \mathcal{Q}_\lambda$.

Remark 1.2. *The operator norm $\|\cdot\|_*$ for the m -th order derivative DN map is defined by*

$$\|A\|_* = \sup \{|\langle A(g, \dots, g), h \rangle| : g, h \in C_c^\infty(\Omega_e), \|g\|_{H^s} = \|h\|_{H^s} = 1\}.$$

One can show that a sufficiently high number of the exterior DN maps uniquely determines a potential in \mathcal{Q}_λ and prove a Lipschitz stability result for the equation (1.1). In order to formulate the result, let us denote the orthogonal projection operators from $H^s(\Omega_e)$ to a subspace H by P_H , i.e. P_H is the linear operator with

$$P_H : H^s(\Omega_e) \rightarrow H, \quad P_H g := \begin{cases} g & \text{if } g \in H, \\ 0 & \text{if } g \in H^\perp \subseteq H^s(\Omega_e). \end{cases}$$

$P'_H : H^* \rightarrow H^s(\Omega_e)^*$ stands for the dual operator of P_H .

Theorem 1.4. *Let $\Omega \subset \mathbb{R}^n$, $n \geq 1$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $m \geq 2$, $m \in \mathbb{N}$. Let $q_1, q_2 \in L^\infty(\Omega)$, and Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. For every sequence of subspaces*

$$H_1 \subseteq H_2 \subseteq H_3 \subseteq \dots \subseteq H^s(\Omega_e), \quad \text{and} \quad \overline{\bigcup_{\ell \in \mathbb{N}} H_\ell} = H^s(\Omega_e),$$

there exists $k \in \mathbb{N}$, and $c > 0$, so that

$$(1.9) \quad \|P'_{H_\ell} ((D^m \Lambda_{q_2})_0 - (D^m \Lambda_{q_1})_0) P_{H_\ell}\|_* \geq c \|q_2 - q_1\|_{L^\infty(\Omega)}$$

for all $q_1, q_2 \in \mathcal{Q}_\lambda$ and all $l \geq k$.

The article is structured as follows. In Section 2, we offer preliminary results for function space (fractional Sobolev spaces and Hölder spaces). We also proved the well-posedness of (1.1), i.e., there exists a unique solution u of (1.1), whenever the

exterior Dirichlet data f are sufficiently small. In Section 3, we derive the monotonicity relations between potentials and its corresponding m -th order derivative DN maps. By combining with the monotonicity relations and localized potentials, we can prove the converse monotonicity relations in Section 4, so that we can prove our main results Theorem 1.1 and Theorem 1.2. We prove the Lipschitz stability results in Section 5. Finally, we recall some known results that the L^p -type estimates of solutions, and the maximum principle of the fractional Laplacian in Appendix A and Appendix B, respectively.

2. PRELIMINARIES

In this section, we introduce function spaces and well-posedness of the Dirichlet problem (1.1). The well-posedness of $(-\Delta)^s u + a(x, u) = 0$ has been proved in [LL20]. We give a similar proof for the sake of completeness under a slightly weaker regularity assumption on the coefficient $a(x, u) = q(x)u^m$, when $q \in L^\infty(\Omega)$ and for $m \geq 2$, $m \in \mathbb{N}$. Let us recall several function spaces which we will use in the rest of the paper.

2.1. Function spaces. Recalling the definition Hölder spaces as follows. Let $D \subset \mathbb{R}^n$ be an open set, $k \in \mathbb{N} \cup \{0\}$ and $0 < \alpha < 1$, then the space $C^{k,\alpha}(D)$ is defined by

$$C^{k,\alpha}(D) := \{f : D \rightarrow \mathbb{R} : \|f\|_{C^{k,\alpha}(D)} < \infty\}.$$

The norm $\|\cdot\|_{C^{k,\alpha}(D)}$ is given by

$$\begin{aligned} \|f\|_{C^{k,\alpha}(D)} &:= \sum_{|\beta| \leq k} \|\partial^\beta f\|_{L^\infty(D)} + \sum_{|\beta|=k} \sup_{\substack{x \neq y, \\ x, y \in D}} \frac{|\partial^\beta f(x) - \partial^\beta f(y)|}{|x - y|^\alpha} \\ &= \sum_{|\beta| \leq k} \|\partial^\beta f\|_{L^\infty(D)} + \sum_{|\beta|=k} [\partial^\beta f]_{C^\alpha(D)} \end{aligned}$$

where $\beta = (\beta_1, \dots, \beta_n)$ is a multi-index with $\beta_i \in \mathbb{N} \cup \{0\}$ and $|\beta| = \beta_1 + \dots + \beta_n$. Here $[\partial^\beta f]_{C^\alpha(D)}$ is denoted as the seminorm of $C^{0,\alpha}(D)$. Furthermore, we also denote the space

$$C_0^{k,\alpha}(D) := \text{closure of } C_c^\infty(D) \text{ in } C^{k,\alpha}(D).$$

We also denote $C^\alpha(D) \equiv C^{0,\alpha}(D)$ when $k = 0$.

We next remind readers in the context of fractional Sobolev spaces. Given $0 < s < 1$, the L^2 -based fractional Sobolev space is $H^s(\mathbb{R}^n) := W^{s,2}(\mathbb{R}^n)$ with the norm

$$\|u\|_{H^s(\mathbb{R}^n)}^2 = \|u\|_{L^2(\mathbb{R}^n)}^2 + \|(-\Delta)^{s/2} u\|_{L^2(\mathbb{R}^n)}^2.$$

Furthermore, via the Parseval identity, the semi-norm $\|(-\Delta)^{s/2} u\|_{L^2(\mathbb{R}^n)}^2$ can be rewritten as

$$\|(-\Delta)^{s/2} u\|_{L^2(\mathbb{R}^n)}^2 = ((-\Delta)^s u, u)_{\mathbb{R}^n},$$

where $(-\Delta)^s$ is the fractional Laplacian (1.2).

Let $D \subset \mathbb{R}^n$ be an open set and $a \in \mathbb{R}$, then we denote the following Sobolev spaces,

$$\begin{aligned} H^a(D) &:= \{u|_D : u \in H^a(\mathbb{R}^n)\}, \\ \tilde{H}^a(D) &:= \text{closure of } C_c^\infty(D) \text{ in } H^a(\mathbb{R}^n), \\ H_0^a(D) &:= \text{closure of } C_c^\infty(D) \text{ in } H^a(D), \end{aligned}$$

and

$$H_D^a := \{u \in H^a(\mathbb{R}^n) : \text{supp}(u) \subset \overline{D}\}.$$

The fractional Sobolev space $H^a(D)$ is complete under the norm

$$\|u\|_{H^a(D)} := \inf \{ \|v\|_{H^a(\mathbb{R}^n)} : v \in H^a(\mathbb{R}^n) \text{ and } v|_D = u \}.$$

Moreover, when D is a Lipschitz domain, the dual spaces can be expressed as

$$(H^s_D(\mathbb{R}^n))^* = H^{-s}(D), \quad \text{and} \quad (H^s(D))^* = H^{-s}_D(\mathbb{R}^n).$$

If reader are interested in the properties of fractional Sobolev spaces, we refer readers to the references [DNPV12, McL00].

2.2. The exterior Dirichlet problem. For $m \geq 2$, $m \in \mathbb{N}$ and $0 < s < 1$. Let $\Omega \subset \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary for $n \geq 1$, and let $q(x) \in L^\infty(\Omega)$. Let us prove the well-posedness for the exterior Dirichlet problem

$$(2.1) \quad \begin{cases} (-\Delta)^s u + qu^m = 0 & \text{in } \Omega, \\ u = f & \text{in } \Omega_e, \end{cases}$$

under the condition that $\|f\|_{C^\infty(\Omega_e)}$ is sufficiently small.

Proposition 2.1 (Well-posedness). *Let $\Omega \subset \mathbb{R}^n$, $n \geq 1$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Suppose that $q = q(x) \in L^\infty(\Omega)$, $m \geq 2$ and $m \in \mathbb{N}$. Then there exists $\varepsilon > 0$ such that when*

$$(2.2) \quad f \in \mathcal{E}_\varepsilon := \{ f \in C^\infty(\Omega_e) : \|f\|_{C^\infty(\Omega_e)} \leq \varepsilon \},$$

the boundary value problem (2.1) has a unique solution u . Furthermore, the following estimate holds

$$(2.3) \quad \|u\|_{C^s(\mathbb{R}^n)} \leq C \|f\|_{C^\infty(\Omega_e)},$$

for some constant $C > 0$, independent of u and f .

Proof. Suppose the smallness condition that $\|f\|_{C^\infty(\Omega_e)} \leq \varepsilon$, for some small number $\varepsilon > 0$, which will be determined later. Following the ideas of [LL20, Theorem 2.1], one can extend f to the whole space \mathbb{R}^n by zero so that $\|f\|_{C^\infty(\mathbb{R}^n)} \leq \varepsilon$. Let u_0 be the solution of the linear Dirichlet problem

$$(2.4) \quad \begin{cases} (-\Delta)^s u_0 = 0 & \text{in } \Omega, \\ u_0 = f & \text{in } \Omega_e. \end{cases}$$

It is easy to see that (2.4) is well-posed, i.e., there exists a unique solution $u_0 \in H^s(\mathbb{R}^n)$ of (2.4).

Let us consider the function $w_0 := u_0 - f$, then $w_0 \in \tilde{H}^s(\Omega)$ is the solution of

$$(2.5) \quad (-\Delta)^s w_0 = -(-\Delta)^s f \quad \text{in } \Omega.$$

Notice that $(-\Delta)^s f$ is also bounded since $\|(-\Delta)^s f\|_{L^\infty(\mathbb{R}^n)} \leq C \|f\|_{C^\infty(\mathbb{R}^n)}$ for some constant $C > 0$ independent of f , by applying the optimal global Hölder regularity [ROS14a, Proposition 1.1] to the equation (2.5) in the bounded $C^{1,1}$ domain Ω , we have

$$\|w_0\|_{C^s(\mathbb{R}^n)} \leq C \|f\|_{C^\infty(\mathbb{R}^n)},$$

for some constant $C > 0$ independent of u_0 and f . Via the triangle inequality, we have that

$$(2.6) \quad \|u_0\|_{C^s(\mathbb{R}^n)} \leq \|w_0\|_{C^s(\mathbb{R}^n)} + \|f\|_{C^s(\mathbb{R}^n)} \leq C \|f\|_{C^\infty(\mathbb{R}^n)},$$

which shows that the solution u_0 of (2.4) is $C^s(\bar{\Omega})$ -continuous.

If u is the solution to (2.1), then $v := u - u_0$ satisfies

$$(2.7) \quad \begin{cases} (-\Delta)^s v = G(v) & \text{in } \Omega, \\ v = 0 & \text{in } \Omega_e. \end{cases}$$

where we denote the operator G by

$$(2.8) \quad G(\phi) := -q(u_0 + \phi)^m.$$

Consider the complete metric space

$$\mathcal{M} = \{\phi \in C^s(\mathbb{R}^n) : \phi|_{\Omega_e} = 0, \|\phi\|_{C^s(\mathbb{R}^n)} \leq \delta\},$$

where $\delta > 0$ will be determined later. We first observe that $G(\phi) = -q(u_0 + \phi)^m \in L^\infty(\Omega)$, when the functions $\phi \in \mathcal{M}$ and $q \in L^\infty(\Omega)$. The reason can be seen by

$$(2.9) \quad \|G(\phi)\|_{L^\infty(\Omega)} \leq C\|q\|_{L^\infty(\bar{\Omega})}\|u_0 + \phi\|_{L^\infty(\Omega)}^m < \infty,$$

which means $G(\phi) \in L^\infty(\Omega)$.

We next want to derive the following result. Let $g \in L^\infty(\Omega)$, then there exists a unique solution $\tilde{v} \in H^s(\mathbb{R}^n)$ to the source problem

$$(2.10) \quad \begin{cases} (-\Delta)^s \tilde{v} = g & \text{in } \Omega, \\ \tilde{v} = 0 & \text{in } \Omega_e. \end{cases}$$

By [ROS14a, Proposition 1.1] again, we have

$$(2.11) \quad \|\tilde{v}\|_{C^s(\mathbb{R}^n)} \leq C\|g\|_{L^\infty(\Omega)},$$

for some constant $C > 0$ independent of g and \tilde{v} .

Let us consider the solution operator of (2.10)

$$\mathcal{L}_s^{-1} : L^\infty(\Omega) \rightarrow C^s(\mathbb{R}^n), \quad g|_\Omega \mapsto \tilde{v}|_\Omega,$$

then we will show that the operator

$$\mathcal{F} := \mathcal{L}_s^{-1} \circ G$$

is a contraction map on \mathcal{M} . Assuming that \mathcal{F} is contraction, by applying the contraction mapping principle on a complete metric space \mathcal{M} , there must exist a fixed point $v \in \mathcal{M}$ such that this fixed point v is the solution of (2.7). To this end, we claim that $\mathcal{F} : \mathcal{M} \rightarrow \mathcal{M}$ and \mathcal{F} is a contraction mapping.

First, by (2.8) and (2.11), one has

$$\begin{aligned} \|\mathcal{F}(\phi)\|_{C^s(\mathbb{R}^n)} &\leq C\|G(\phi)\|_{L^\infty(\Omega)} \\ &\leq C\|q|\phi + u_0|^m\|_{L^\infty(\Omega)} \\ &\leq C\|u_0 + \phi\|_{L^\infty(\Omega)}^m \\ &\leq C\|u_0 + \phi\|_{C^s(\bar{\Omega})}^m \\ &\leq C(\delta + \varepsilon)^m, \end{aligned}$$

for any $\phi \in \mathcal{M}$, for some constant $C > 0$ independent of ϕ and u_0 . In addition, one can also obtain that

$$\|\mathcal{F}(\phi)\|_{C^s(\mathbb{R}^n)} \leq C(\varepsilon + \delta)^m < \delta,$$

where we have used $m \geq 2$ and $m \in \mathbb{N}$ such that \mathcal{F} maps \mathcal{M} into \mathcal{M} itself for ε and δ small enough.

Second, we want to show that \mathcal{F} is a contraction mapping. By using straightforward computations, from (2.11) and the mean value theorem, we have

$$\begin{aligned} &\|\mathcal{F}(\phi_1) - \mathcal{F}(\phi_2)\|_{C^s(\mathbb{R}^n)} \\ &= \|(\mathcal{L}_s^{-1} \circ G)(\phi_1) - (\mathcal{L}_s^{-1} \circ G)(\phi_2)\|_{C^s(\mathbb{R}^n)} \\ &\leq C\|G(\phi_1) - G(\phi_2)\|_{L^\infty(\Omega)} \\ &\leq C\|(\phi_1 + u_0)^m - (\phi_2 + u_0)^m\|_{L^\infty(\Omega)} \\ &\leq C\|m|u_0 + \theta\phi_1 + (1 - \theta)\phi_2|^{m-1}|\phi_2 - \phi_1|\|_{L^\infty(\Omega)} \\ &\leq C\|u_0 + \theta\phi_1 + (1 - \theta)\phi_2\|_{L^\infty(\Omega)}^{m-1}\|\phi_2 - \phi_1\|_{C^s(\bar{\Omega})}, \end{aligned}$$

for some $0 < \theta < 1$ and for some constant $C > 0$ independent of u_0 , ϕ_1 and ϕ_2 . This infers that

$$\|\mathcal{F}(\phi_1) - \mathcal{F}(\phi_2)\|_{C^s(\mathbb{R}^n)} \leq C(\varepsilon + \delta)^{m-1} \|\phi_2 - \phi_1\|_{C^s(\mathbb{R}^n)}$$

for some constant $C_0 > 0$ independent of $\phi_1, \phi_2, \varepsilon$ and δ . Now, by choosing ε, δ sufficiently small, we obtain that $C(\varepsilon + \delta)^{m-1} < 1$ due to $m \geq 2$, which concludes that \mathcal{F} is a contraction mapping on the complete metric space \mathcal{M} .

In summary, there must exist a unique solution $v \in \mathcal{M}$ to the equation (2.7), such that v satisfies

$$\begin{aligned} \|v\|_{C^s(\mathbb{R}^n)} &\leq C \left(\|u_0\|_{C^s(\bar{\Omega})}^m + \|v\|_{C^s(\bar{\Omega})}^m \right) \\ &\leq C \left(\varepsilon^{m-1} \|f\|_{C_c^\infty(\Omega_e)} + \delta^{m-1} \|v\|_{C^s(\bar{\Omega})} \right), \end{aligned}$$

where we have used (2.6). For δ sufficiently small and $m \geq 2$, $m \in \mathbb{N}$, we can then derive that

$$(2.12) \quad \|v\|_{C^s(\mathbb{R}^n)} \leq C \|f\|_{C_c^\infty(\Omega_e)}.$$

Meanwhile, via (2.6) and (2.12), the solution $u = u_0 + v \in C^s(\mathbb{R}^n)$ to the Dirichlet problem (2.1) satisfies the desired estimate

$$\|u\|_{C^s(\mathbb{R}^n)} \leq C \|f\|_{C_c^\infty(\Omega_e)},$$

for some constant $C > 0$ independent of u and f . This completes the proof of the well-posedness. \square

Remark 2.2. Via Proposition 2.1, as a matter of fact, one can that the solution u of (2.1) is in $C_c^s(\mathbb{R}^n)$, when $u = f \in C_c^\infty(\Omega_e)$ in Ω_e . Moreover, we can derive that $u \in H^s(\mathbb{R}^n)$, by the following straightforward computations. Consider the function $w = u - f$, where u is the solution of (2.1) and $f \in C_c^\infty(\Omega_e) \subset C_c^\infty(\mathbb{R}^n)$. Then w is the solution of

$$(2.13) \quad \begin{cases} (-\Delta)^s w + w = -qu^m + u - f - (-\Delta)^s f & \text{in } \Omega, \\ w = 0 & \text{in } \Omega_e. \end{cases}$$

By multiplying w to (2.13) and integrating over \mathbb{R}^n , we can derive that $w \in H^s(\mathbb{R}^n)$, where we have utilized the estimate (2.3). Hence, $u = w + f \in H^s(\mathbb{R}^n)$.

We can define the DN map rigorously as follows.

Proposition 2.3 (The DN map). *Let $\Omega \subset \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$ for $n \geq 1$, $0 < s < 1$ and let $q \in L^\infty(\Omega)$. Define*

$$(2.14) \quad \langle \Lambda_q f, \varphi \rangle := \int_{\mathbb{R}^n} (-\Delta)^{s/2} u_f (-\Delta)^{s/2} \varphi \, dx + \int_{\Omega} q u_f^m \varphi \, dx,$$

for $f, \varphi \in C_c^\infty(\mathbb{R}^n)$. The function $u_f \in C^s(\mathbb{R}^n) \cap H^s(\mathbb{R}^n)$ is the solution of (2.1) with the sufficiently small exterior data $f \in C_c^\infty(\Omega_e)$. Then the DN map

$$\Lambda_q : H^s(\Omega_e) \rightarrow H^s(\Omega_e)^*$$

is bounded, and

$$(2.15) \quad \Lambda_q f|_{\Omega_e} = (-\Delta)^s u_f|_{\Omega_e}.$$

Proof. Notice that (2.14) is not a bilinear form, since qu^m is not a linear function. By using the Parseval identity, we have that

$$\begin{aligned} & \int_{\mathbb{R}^n} (-\Delta)^{s/2} u_f (-\Delta)^{s/2} \varphi \, dx + \int_{\Omega} q u_f^m \varphi \, dx \\ &= \int_{\mathbb{R}^n} (-\Delta)^s u_f \varphi \, dx + \int_{\Omega} q u_f^m \varphi \, dx \\ &= \int_{\Omega_e} (-\Delta)^s u_f \varphi \, dx, \end{aligned}$$

where we have utilized that $u_f \in H^s(\mathbb{R}^n)$ is the solution of (2.1) as in Remark 2.2 and

$$\int_{\mathbb{R}^n} (-\Delta)^s u_f \varphi \, dx = \int_{\Omega} (-\Delta)^s u_f \varphi \, dx + \int_{\Omega_e} (-\Delta)^s u_f \varphi \, dx.$$

The preceding identity was justified in [GSU20]. Since $\varphi \in C_c^\infty(\mathbb{R}^n) \subset H^s(\mathbb{R}^n)$ is arbitrary, by the duality argument, then we prove the proposition. \square

Notice that for the nonlinearities $q(x)u^m$, the higher order linearizations of the exterior DN map Λ_q is particularly simple (see [LLLS20a, Section 2] for the local case $s = 1$). It is slightly different from the earlier work [LLLS20a], which adapts multiple small parameters to do the higher order linearization. Instead, we use the ideas from [LL20], via a single ϵ parameter to do the higher order linearization for fractional semilinear equations.

Let $\epsilon > 0$ be a sufficiently small number, and $g \in C_c^\infty(\Omega_e)$. The next proposition demonstrates that we may differentiate the fractional semilinear equation

$$(2.16) \quad \begin{cases} (-\Delta)^s u + q(x)u^m = 0 & \text{in } \Omega, \\ u = \epsilon g & \text{in } \Omega_e, \end{cases}$$

formally in the ϵ variable to have equations corresponding to first linearization and m -th linearization that

$$(2.17) \quad \begin{cases} (-\Delta)^s v_g = 0 & \text{in } \Omega, \\ v_g = g & \text{in } \Omega_e, \end{cases}$$

and

$$(2.18) \quad \begin{cases} (-\Delta)^s w = -(m!)q(v_g)^{m+1} & \text{in } \Omega, \\ w = 0 & \text{in } \Omega_e, \end{cases}$$

respectively. We call the solution v_g of the fractional Laplacian equation (2.17) to be s -harmonic in the rest of paper.

The DN map of the solution w of (2.18) is the m -th linearization of the DN map of (2.16). Let

$$(D^k T)_x(y_1, \dots, y_k)$$

denote the k -th derivative at x of a mapping T between Banach spaces, which can be regarded as a symmetric k -linear form acting on (y_1, \dots, y_k) . We refer to [Hor85, Section 1.1], where the notation $T^{(k)}(x; y_1, \dots, y_k)$ is used instead of $(D^k T)_x(y_1, \dots, y_k)$.

For $f \in C_c^\infty(\Omega_e)$ with $\|f\|_{C_c^\infty(\Omega_e)}$ to be sufficiently small. By using the notation of s -harmonic function v_g given by (2.17), we have the following result.

Proposition 2.4. *Let $\Omega \subset \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$ for $n \geq 1$, $0 < s < 1$ and let $q \in L^\infty(\Omega)$. Let Λ_q be the DN map for the fractional semilinear elliptic equation*

$$(2.19) \quad (-\Delta)^s u + qu^m = 0 \text{ in } \Omega,$$

where $m \in \mathbb{N}$ and $m \geq 2$. The first linearization $(D\Lambda_q)_0$ of Λ_q at $g = 0$ is the DN map of the fractional Laplacian (2.17) such that

$$(D\Lambda_q)_0 : H^s(\Omega_e) \rightarrow H^s(\Omega_e)^*, \quad g \mapsto (-\Delta)^s v_g|_{\Omega_e}.$$

The higher order linearizations $(D^j \Lambda(q))_0$ are identically zero for $2 \leq j \leq m - 1$.

The m -th linearization $(D^m \Lambda_q)_0$ of Λ_q at $g = 0$ can be characterized by

$$(2.20) \quad \int_{\Omega_e} (D^m \Lambda_q)_0(g, \dots, g) h \, dx = (m!) \int_{\Omega} q(v_g)^m v_h \, dx,$$

where v_g and v_h are s -harmonic in Ω with the exterior value $v_g = g$ and $v_h = h$ in Ω_e , respectively.

Remark 2.5. We point out:

- (a) Even though the original DN map Λ_q depends on q non-linearly, but it is worth emphasizing that the integral identity (2.20) implies that the m -th order derivative of Λ_q depends linearly on q .
- (b) Proposition 2.4 plays an essential role to prove our main results of this article.

Proof of Proposition 2.4. Via Proposition 2.1, and thus the DN map $\Lambda_q(f) = (-\Delta)^s(Sf)|_{\Omega_e}$ is well defined for sufficiently small exterior data f , where $S : f \mapsto u_f$ is the solution operator for the equation (2.19). In order to compute the derivatives of Λ_q at 0, it suffices to consider the derivatives of S . Furthermore, by using Proposition 2.1, the maps

$$\begin{aligned} S : \mathcal{E}_\delta &\rightarrow H^s(\mathbb{R}^n), & f &\mapsto u_f, \\ \Lambda_q : \mathcal{E}_\delta &\rightarrow H^s(\Omega_e)^*, & f &\mapsto (-\Delta)^s u_f|_{\Omega_e} \end{aligned}$$

are C^∞ Fréchet differentiable mappings, where \mathcal{E}_δ is the set defined by (2.2) to denote the set of small exterior data.

Let us write $f = f(x; \epsilon) := \epsilon g(x) \in C_c^\infty(\Omega_e)$, then the function $u_{\epsilon g} = S(\epsilon g) \in C^s(\bar{\Omega})$ depends smoothly on the small parameter ϵ . By applying $\partial_\epsilon^m|_{\epsilon=0}$ to the Taylor's formula for C^∞ Fréchet differentiable mappings (see e.g. [Hor85, Equation 1.1.7])

$$S(f) = \sum_{j=0}^k \frac{(D^j S)_0(f, \dots, f)}{j!} + \int_0^1 \frac{(D^{k+1} S)_{tf}(f, \dots, f)}{k!} (1-t)^k \, dt$$

implies that $(D^k S)_0$ may be computed using the formula

$$(D^k S)_0(f, \dots, f) = \partial_\epsilon^k u_f|_{\epsilon=0}.$$

Moreover, since u_f is smooth in the ϵ variables and the fractional Laplacian $(-\Delta)^s$ is linear, one may differentiate the equation

$$(2.21) \quad (-\Delta)^s u_f + q u_f^m = 0 \text{ in } \Omega, \quad u_f = f \text{ in } \Omega_e$$

with respect to the ϵ variable.

For the first linearization $k = 1$ with $u = u_{\epsilon g}$, we have $u_0 = 0$ in \mathbb{R}^n and $m \geq 2$, the derivative of (2.21) in ϵ evaluated at $\epsilon = 0$ satisfies

$$(-\Delta)^s (\partial_\epsilon|_{\epsilon=0} u_f) = 0 \text{ in } \Omega, \quad \partial_\epsilon|_{\epsilon=0} u_f = g \text{ in } \Omega_e.$$

Thus the first linearization of the map S at $f = 0$ ($f = \epsilon g$ with $\epsilon = 0$) is

$$(DS)_0(g) = \partial_\epsilon|_{\epsilon=0} u_{\epsilon g} = v_g, \quad \text{for } g \in C_c^\infty(\Omega_e),$$

where v_g is s -harmonic in Ω with $v_g = g$ in Ω_e .

For $2 \leq k \leq m-1$, applying the k -th order derivatives $\partial_\epsilon^k|_{\epsilon=0}$ to (2.21) gives that

$$(-\Delta)^s (\partial_\epsilon^k|_{\epsilon=0} u_f) = 0 \text{ in } \Omega, \quad \partial_\epsilon^k|_{\epsilon=0} u_f = 0 \text{ in } \Omega_e,$$

since $\partial_\epsilon^k (q(x)u_f^m)$ is a sum of terms containing positive powers of the solution u_f , which are equal to zero whenever $\epsilon = 0$. The uniqueness of solutions for the fractional Laplace equation implies that

$$\underbrace{(D^k S)_0}_{k\text{-linear form}} \underbrace{(g, \dots, g)}_{k\text{-vector}} = 0, \quad \text{for } 2 \leq k \leq m-1.$$

More precisely, we have used the fact that any s -harmonic function with 0 exterior data is zero in \mathbb{R}^n .

When $k = m$, the only nonzero term in the expansion of $\partial_\epsilon^m|_{\epsilon=0} (q(x)u_f^m)$ does not contain second or higher order derivatives of u_f with respect to ϵ . The nonzero term after inserting $\epsilon = 0$ is

$$q(x)(m!) (\partial_\epsilon|_{\epsilon=0} u_f)^m = q(x)(m!)(v_g)^m.$$

Hence, the function

$$w := (D^m S)_0(g, \dots, g) = \partial_\epsilon^m|_{\epsilon=0} u_f \quad \text{in } \mathbb{R}^n$$

solves

$$(2.22) \quad (-\Delta)^s w + q(x)(m!)(v_g)^m = 0 \quad \text{in } \Omega,$$

with zero exterior data in Ω_e .

By linearity we have

$$(D^k \Lambda_q)_0|_{\Omega_e} = (-\Delta)^s (D^k S)_0|_{\Omega_e}.$$

The claims for derivatives of DN map $(D^k \Lambda_q)_0$ when $1 \leq k \leq m-1$ follow immediately. For $k = m$ we observe that $(D^m \Lambda_q)_0(g, \dots, g) = (-\Delta)^s w|_{\Omega_e}$ satisfies

$$(2.23) \quad \begin{aligned} \int_{\Omega_e} ((-\Delta)^s w) h \, dx &= \int_{\mathbb{R}^n} (-\Delta)^s w v_h \, dx + m! \int_{\Omega} q v^m v_h \, dx \\ &= m! \int_{\Omega} q v^m v_h \, dx, \end{aligned}$$

where v_h is s -harmonic in Ω with $v_h = h$ in Ω_e . Finally, we have used that $\int_{\mathbb{R}^n} (-\Delta)^s w h \, dx = 0$ in (2.23) due to the Parseval's identity that

$$\int_{\mathbb{R}^n} (-\Delta)^s w h \, dx = \int_{\mathbb{R}^n} w (-\Delta)^s h \, dx = \underbrace{\int_{\Omega} w (-\Delta)^s h \, dx}_{(-\Delta)^s h=0 \text{ in } \Omega} + \underbrace{\int_{\Omega_e} w (-\Delta)^s h \, dx}_{w=0 \text{ in } \Omega_e} = 0.$$

Thus, the proposition follows by using (2.22). \square

For the sake of convenience, in the rest of this paper, let us utilize the pairing notation

$$\langle \underbrace{(D^m \Lambda_q)_0}_{m\text{-form}} \underbrace{(g, \dots, g)}_{m\text{-vectors}}, h \rangle = \int_{\Omega_e} (D^m \Lambda_q)_0(g, \dots, g) h \, dx,$$

where $(D^m \Lambda_q)_0 : H^s(\Omega_e)^m \rightarrow H^s(\Omega_e)^*$ is regarded as an m -form acting on an m -vector valued function (g, \dots, g) .

Let $\Omega \subset \mathbb{R}^n$, $n \geq 1$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $q_1, q_2 \in L^\infty(\Omega)$, and Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. As we mentioned in Proposition 2.4, there

are no information of $(D^k \Lambda_{q_j})_0$ for any $k = 2, \dots, m-1$. Let us look at the case $k = 0$ and $k = 1$. For $k = 0$, we have that

$$(D^0 \Lambda_{q_j})_0 = \Lambda_{q_j}(\epsilon g)|_{\epsilon=0} = 0, \quad \text{for } j = 1, 2,$$

due to the well-posedness of (2.1). Meanwhile, for the case $k = 1$, the map $(D^1 \Lambda_{q_j})_0$ denotes the DN map of the fractional Laplacian equation (2.17), for $j = 1, 2$, which has no unknown coefficients in the equation (2.17). Hence, we must have

$$(D^1 \Lambda_{q_1})_0 = (D^1 \Lambda_{q_2})_0.$$

Therefore, in order to understand the relations of the DN maps Λ_{q_j} , one can obtain the information of the m -th order derivative $(D^m \Lambda_{q_j})_0$ of the DN map Λ_{q_j} , for $j = 1, 2$.

3. MONOTONICITY AND LOCALIZED POTENTIALS

In this section, we show monotonicity relations between potentials q and their corresponding DN maps, and we demonstrate how to control the energy terms in the monotonicity formulas with the localized potentials of the fractional Laplacian.

3.1. Monotonicity relations. We study the monotonicity relations between the m -th order derivative of DN maps and the potentials via the following integral identity. Let us define the energy inequalities of the m -th order derivative of DN maps:

Definition 3.1. Consider $\Omega \subset \mathbb{R}^n$, $n \geq 1$ to be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $q_1, q_2 \in L^\infty(\Omega)$, $m \geq 2$ and $m \in \mathbb{N}$. Let Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. Then the inequality $(D^m \Lambda_{q_1})_0 \geq (D^m \Lambda_{q_2})_0$ can be defined as follows:

(a) When m is odd, $(D^m \Lambda_{q_1})_0 \geq (D^m \Lambda_{q_2})_0$ is denoted by

$$(3.1) \quad \langle [(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0](g, \dots, g), g \rangle \geq 0,$$

for any $g \in C_c^\infty(\Omega_e)$.

(b) When m is even, $(D^m \Lambda_{q_1})_0 \geq (D^m \Lambda_{q_2})_0$ is denoted by

$$(3.2) \quad \langle [(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0](g, \dots, g), h \rangle \geq 0,$$

for any $g, h \in C_c^\infty(\Omega_e)$ with $h \geq 0$.

We next demonstrate the monotonicity relations between potentials and the m -th order derivatives of the DN map. Due the particular structure of the power type nonlinearities, the integral identity will imply the monotonicity formulas directly, which is a more straightforward result than its linear counterpart.

Theorem 3.1 (Monotonicity relations). Consider $\Omega \subset \mathbb{R}^n$, $n \geq 1$ to be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $q_1, q_2 \in L^\infty(\Omega)$, $m \geq 2$ and $m \in \mathbb{N}$. Let Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. Then

(a) We have the integral identity

$$(3.3) \quad \langle [(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0](g, \dots, g), h \rangle = (m!) \int_{\Omega} (q_1 - q_2)(v_g)^m v_h \, dx$$

where v_g and v_h are s -harmonic in Ω with $v_g = g$ and $v_h = h$ in Ω_e , respectively, for $g, h \in C_c^\infty(\Omega_e)$.

(b) We have the monotonicity relation

$$q_1 \geq q_2 \text{ in } \Omega \quad \text{implies that} \quad (D^m \Lambda_{q_1})_0 \geq (D^m \Lambda_{q_2})_0.$$

Proof. For (a), the proof is a simple application of Proposition 2.4. Via (2.20), one has

$$\langle (D^m \Lambda_{q_j})_0(g, \dots, g), h \rangle = \int_{\Omega_e} (D^m \Lambda_{q_j})_0(g, \dots, g) h \, dx = (m!) \int_{\Omega} q_j (v_g)^m v_h \, dx,$$

for $j = 1, 2$. By subtracting the preceding identity with $j = 1$ and $j = 2$, we have the desired identity (3.3).

For (b), we first show the case when m is odd. Let us take $h = g \in C_c^\infty(\Omega_e)$, then the uniqueness of the fractional Laplacian implies that $v_g = v_h$ in Ω . By plugging $q_1 - q_2 \geq 0$ in Ω into (3.3), we must have

$$\langle [(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0](g, \dots, g), g \rangle = (m!) \int_{\Omega} (q_1 - q_2) (v_g)^{m+1} \, dx \geq 0,$$

where we have used that m is odd so that $(v_g)^{m+1} = |v_g|^{m+1} \geq 0$ in Ω . This satisfies (3.1) so that $(D^m \Lambda_{q_1})_0 \geq (D^m \Lambda_{q_2})_0$.

When m is even, we take $h \in C_c^\infty(\Omega_e)$ with $h \geq 0$. Note that v_h is s -harmonic in Ω with $v_h = h \geq 0$ in Ω_e , then the maximum principle for the fractional Laplacian yields that $v_h \geq 0$ in Ω (for example, see [RO16]). By plugging $q_1 - q_2 \geq 0$ in Ω into (3.3), we must have

$$\langle [(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0](g, \dots, g), h \rangle = (m!) \int_{\Omega} (q_1 - q_2) (v_g)^m v_h \, dx \geq 0,$$

where we have used that m is even so that $(v_g)^m = |v_g|^m \geq 0$ in Ω and $v_h \geq 0$ in Ω . This satisfies (3.2) so that $(D^m \Lambda_{q_1})_0 \geq (D^m \Lambda_{q_2})_0$. This completes the proof. \square

Remark 3.2. From Theorem 3.1, we have:

- (a) In the proof of part (b) of Theorem 3.1, one can see that why we need to choose different s -harmonic function v_h in (3.3) so that (3.1) and (3.2) have correct sign conditions. In particular, when $h \leq 0$ in Ω_e , the maximum principle (see Appendix B) yields that $(D^m \Lambda_{q_1})_0 \leq (D^m \Lambda_{q_2})_0$, provided that $q_1 \geq q_2$ in Ω . However, for general $h \in C_c^\infty(\Omega_e)$, we do not know the sign condition of the s -harmonic function v_h in Ω so that we cannot have the monotonicity relation as in Theorem 3.1 (b).
- (b) In particular, when $m = 1$, i.e., for the (linear) fractional Schrödinger equation, one can adapt (3.2) as the monotonicity assumption. One can see that if we do the "linearization" to the fractional Schrödinger equation, then the "linearized" equation is also the same fractional Schrödinger equation. The monotonicity relations were derived in the works [HL19, HL20].
- (c) In the semilinear case, the monotonicity relation between potentials and m -th order derivative of DN maps is equivalent to the integral identity (3.3), which makes the monotonicity tests be easier for the fractional semilinear elliptic equation than their linear counterparts.

3.2. Localized potentials for the fractional Laplacian. We demonstrate the existence of localized potentials for s -harmonic functions. For the fractional Laplacian, the existence of localized potentials is a simple consequence of the strong uniqueness and Runge approximation, which was demonstrated by [GSU20]. In this work, we use slightly different settings. For the sake of completeness, let us state the the strong uniqueness, Runge approximation, and localized potentials as follows.

Proposition 3.3 (Strong uniqueness). *For $n \geq 1$, $0 < s < 1$, let $v \in L^p(\mathbb{R}^n)$ for some $1 < p < 2$ satisfy both v and $(-\Delta)^s v$ vanish in the same arbitrary non-empty open set in \mathbb{R}^n , then $v \equiv 0$ in \mathbb{R}^n .*

The preceding proposition was shown in the proof of [GSU20, Theorem 1.2] for the case $v \in H^a(\mathbb{R}^n)$ for some $a \in \mathbb{R}$. In particular, Proposition 3.3 was recently proved by Covi-Mönkkönen-Railo [CMR20, Corollary 4.5].

We next prove the Runge approximation, and the mathematical settings are slightly different from [GSU20]. In [GSU20], the authors proved any L^2 functions can be approximated by solutions of the fractional Schrödinger equation. In this work, our aim is only to demonstrate that any L^a -integrable functions for $a > 1$, can be approximated by a sequence of s -harmonic functions.

Theorem 3.2 (Runge approximation for the fractional Laplacian). *For $n \geq 1$, $0 < s < 1$, let $\Omega \subseteq \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $O \Subset \Omega_e = \mathbb{R}^n \setminus \bar{\Omega}$ be open. Let $m \geq 2$, $m \in \mathbb{N}$. Given an arbitrary $a > 1$, for every $\varphi \in L^a(\Omega)$ there exists a sequence $g^k \in C_c^\infty(O)$, so that the corresponding solutions $v^k \in H^s(\mathbb{R}^n)$ to*

$$(-\Delta)^s v^k = 0 \text{ in } \Omega, \quad u^k = g^k \text{ in } \Omega_e,$$

satisfy that $v^k|_\Omega \rightarrow \varphi$ in $L^a(\Omega)$ as $k \rightarrow \infty$.

Proof. The idea of the proof is similar to the proof of [GSU20, Theorem 1.3], but we will use the fact that if v is the solution of $(-\Delta)^s v = 0$ in Ω with $v = g \in C_c^\infty(\Omega_e)$, then the well-posedness yields that $v \in H^s(\mathbb{R}^n)$. Furthermore, by using the global Hölder estimate [ROS14a, Proposition 1.1], one has $v \in C^s(\mathbb{R}^n)$.

In order to prove the theorem, let us consider the set

$$\mathbb{D} = \{v_g|_\Omega; g \in C_c^\infty(O)\},$$

where $v_g \in H^s(\mathbb{R}^n)$ is the unique solution of

$$(3.4) \quad \begin{cases} (-\Delta)^s v_g = 0 & \text{in } \Omega, \\ v_g = g & \text{in } \Omega_e, \end{cases}$$

with $g \in C_c^\infty(\Omega_e)$. Then \mathbb{D} is dense in $L^a(\Omega)$. Via [ROS14a, Proposition 1.1], it is easy to see that $\mathbb{D} \subset C^s(\bar{\Omega})$ which implies $\mathbb{D} \subset L^a(\Omega)$, for all $a > 1$. By the Hahn-Banach theorem, it suffices to show that for any function $\varphi \in L^r(\Omega)$ satisfying $\int_\Omega \varphi v_g dx = 0$ for any $v \in \mathbb{D}$, where $\frac{1}{r} + \frac{1}{a} = 1$, then $\varphi \equiv 0$.

Let φ be a such function, which means φ satisfies

$$(3.5) \quad \int_\Omega \varphi v_g dx = 0, \quad \text{for any } g \in C_c^\infty(O).$$

Next, let ϕ be the solution of

$$\begin{cases} (-\Delta)^s \phi = \varphi & \text{in } \Omega, \\ \phi = 0 & \text{in } \Omega_e. \end{cases}$$

By using the L^p estimate for the fractional Laplacian (see Proposition A.3 and Remark A.4), we know that $\phi \in L^p(\Omega)$ for some $p \in (1, 2)$ since $\varphi \in L^r(\Omega)$ for some $r > 1$.

We next claim that for any $g \in C_c^\infty(O)$, the following relation

$$(3.6) \quad \int_\Omega \varphi v_g dx = - \int_{\mathbb{R}^n} (-\Delta)^{s/2} \phi (-\Delta)^{s/2} g dx$$

holds. In other words, $\int_{\mathbb{R}^n} (-\Delta)^{s/2} \phi (-\Delta)^{s/2} w dx = \int_\Omega \varphi w dx$ for any $w \in \mathbb{D} \subset L^a(\Omega)$. In order to prove (3.6), let $g \in C_c^\infty(O)$, and v_g be the solution of (3.4).

Then by [ROS14a, Proposition 1.1], we have $v_g \in C^s(\mathbb{R}^n)$ with $v_g - g \in C_0^s(\Omega)$ and

$$\begin{aligned} \int_{\Omega} \varphi v_g dx &= \int_{\Omega} \varphi(v_g - g) dx \\ &= \int_{\mathbb{R}^n} (-\Delta)^{s/2} \phi \cdot (-\Delta)^{s/2} (v_g - g) dx \\ &= - \int_{\mathbb{R}^n} (-\Delta)^{s/2} \phi \cdot (-\Delta)^{s/2} g dx, \end{aligned}$$

where we have utilized that v_g is s -harmonic in Ω and $\phi = 0$ in Ω_e .

Hence, (3.5) and (3.6) yield that imply that

$$\int_{\mathbb{R}^n} (-\Delta)^{s/2} \phi (-\Delta)^{s/2} g dx = 0, \quad \text{for any } g \in C_c^\infty(O).$$

Moreover, we know that $g|_{\Omega} = 0$ due to $g \in C_c^\infty(O)$, then the Parseval's identity infers that

$$\int_{\mathbb{R}^n} (-\Delta)^s \phi g dx = 0, \quad \text{for any } g \in C_c^\infty(O).$$

In the end, we know that $\phi \in L^p(\Omega)$ with $\phi = 0$ in Ω_e , which satisfies $\phi \in L^p(\mathbb{R}^n)$ for some $p \in (1, 2)$, and

$$\phi|_O = (-\Delta)^s \phi|_O = 0.$$

By applying Proposition 3.3, we obtain $\phi \equiv 0$ in \mathbb{R}^n so that $v \equiv 0$ as desired. \square

Based on the Runge approximation, one can obtain the existence of the localized potentials immediately.

Corollary 3.4 (Localized potentials). *For $n \geq 1$, let $\Omega \subseteq \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, $0 < s < 1$, and $O \subseteq \Omega_e = \mathbb{R}^n \setminus \overline{\Omega}$ be an arbitrary open set. For any $a > 1$ and every measurable set $M \subseteq \Omega$, there exists a sequence $g^k \in C_c^\infty(O)$, so that the corresponding solutions $v^k \in H^s(\mathbb{R}^n)$ of*

$$(3.7) \quad (-\Delta)^s v^k = 0 \quad \text{in } \Omega, \quad v^k|_{\Omega_e} = g^k, \quad \text{for all } k \in \mathbb{N}$$

satisfy that

$$\int_M |v^k|^a dx \rightarrow \infty \quad \text{and} \quad \int_{\Omega \setminus M} |v^k|^a dx \rightarrow 0 \quad \text{as } k \rightarrow \infty.$$

Proof. The proof is based on the Runge approximation (Theorem 3.2) and the normalization argument. By Theorem 3.2, there exists a sequence $\tilde{g}^k \in C_c^\infty(\Omega_e)$ so that the corresponding solutions $\tilde{v}^k|_{\Omega}$ converge to $\left(\frac{1}{|M|}\right)^{\frac{1}{a}} \chi_M$ in $L^a(\Omega)$, where $|M|$ denotes the Lebesgue measure of the measurable set M . This implies that

$$\|\tilde{v}^k\|_{L^a(M)}^a = \int_M |\tilde{v}^k|^a dx \rightarrow 1, \quad \text{and} \quad \|\tilde{v}^k\|_{L^a(\Omega \setminus M)}^a = \int_{\Omega \setminus M} |\tilde{v}^k|^a dx \rightarrow 0,$$

as $k \rightarrow \infty$.

Without loss of generality, we can assume for all $k \in \mathbb{N}$ that $\tilde{v}^k \not\equiv 0$, so that $\|\tilde{v}^k\|_{L^a(\Omega \setminus M)} > 0$ follows due to the strong uniqueness of the fractional Laplacian (Proposition 3.3). Assume that the normalized exterior data

$$g^k := \frac{\tilde{g}^k}{\|\tilde{v}^k\|_{L^a(\Omega \setminus M)}^{1/a}} \in C_c^\infty(\Omega_e),$$

then the sequence of corresponding solutions $v^k \in C^s(\mathbb{R}^n)$ of (3.7) has the desired property that

$$(3.8) \quad \|v^k\|_{L^a(M)}^a = \frac{\|\tilde{v}^k\|_{L^a(M)}^a}{\|\tilde{v}^k\|_{L^a(\Omega \setminus M)}^a} \rightarrow \infty, \quad \text{and} \quad \|v^k\|_{L^a(\Omega \setminus M)}^a = \|\tilde{v}^k\|_{L^a(\Omega \setminus M)}^{a-1} \rightarrow 0,$$

as $k \rightarrow \infty$, where we have used the exponent $a > 1$. \square

Remark 3.5. *The construction of the localized potentials for is based on the Runge approximation for the fractional Laplacian, which is a linear fractional differential equation. Notice that one might be able to study the approximation property for the fractional semilinear elliptic equation $(-\Delta)^s u + qu^m = 0$ for $m \geq 2$, $m \in \mathbb{N}$, however, one cannot expect the existence of the localized potential for fractional semilinear equations. The reason is due to the well-posedness (Proposition 2.1), which requires sufficiently small exterior data, such that the solution is small as well. Therefore, the well-posedness for the fractional semilinear elliptic equation (1.1) is an obstruction to construct the energy concentration on any (positive) measurable region inside a given domain. This implies that the L^a -norm of the normalized solution (see (3.8)) can be arbitrarily large in some region is impossible.*

4. CONVERSE MONOTONICITY, UNIQUENESS, AND INCLUSION DETECTION

This section consists the proof of the first main result of the work. With the localized potentials (3.8) and the integral identity (3.3) at hand, we can extend Theorem 3.1 to an if-and-only-if statement.

4.1. Converse monotonicity and the fractional Calderón problem. Let us prove the if-and-only-if monotonicity relation between the potential and the m -th order derivative of the DN map.

Proof of Theorem 1.1. Via Theorem 3.1, $q_1 \geq q_2$ a.e. in Ω implies $(D_0^m \Lambda_{q_1})_0 \geq (D_0^m \Lambda_{q_2})_0$ (in the sense of Definition 3.1). The conclusion holds if we can show that $(D_0^m \Lambda_{q_1})_0 \geq (D_0^m \Lambda_{q_2})_0$ implies $q_1 \geq q_2$ a.e. in Ω .

Suppose that $(D_0^m \Lambda_{q_1})_0 \geq (D_0^m \Lambda_{q_2})_0$ holds, then the integral identity (3.3) yields that

$$(4.1) \quad \int_{\Omega} (q_1 - q_2)(v_g)^m v_h \, dx \geq 0,$$

where $v_g = v_h$ if m is odd and $v_h \geq 0$ if m is even (see Definition 3.1 and Theorem 3.1). In order to show that $q_1 \geq q_2$ in Ω , we prove it by a standard contradiction argument. Suppose that there exists a constant $\delta > 0$ and a positive measurable subset $M \subset \Omega$ such that $q_2 - q_1 \geq \delta > 0$ in M . By applying the localized potentials from Corollary 3.4 for an appropriate exponent $a > 1$, which will be determined later. Hence, there must exist a sequence $\{g^k\}$ such that the corresponding s -harmonic functions v^k with $v^k = g^k$ in Ω_e satisfy

$$(4.2) \quad \int_M |v^k|^a \, dx \rightarrow \infty \quad \text{and} \quad \int_{\Omega \setminus M} |v^k|^a \, dx \rightarrow 0,$$

as $k \rightarrow \infty$.

Combine with (4.1), then we have:

- (a) When m is odd, we take the s -harmonic functions $v_g = v_h$ to be the localized potentials $\{v^k\}$ into (3.3) such that

$$\begin{aligned} 0 &\leq \int_{\Omega} (q_1 - q_2) |v^k|^{m+1} dx \\ &\leq -\delta \int_M |v^k|^{m+1} dx + \|q_1 - q_2\|_{L^\infty(\Omega)} \int_{\Omega \setminus M} |v^k|^{m+1} dx \\ &\rightarrow -\infty, \end{aligned}$$

as $k \rightarrow \infty$, where we have utilized (4.2) as the exponent $a = m + 1$, then

- (b) When m is even, we need to use the other monotonicity definition 3.2. In this case, we choose the exterior data $h \in C_c^\infty(\Omega_e)$, $h \geq 0$ and $h \not\equiv 0$. Then by the maximum principle (Proposition B.1) in Appendix B, we must have $v_h > 0$ in Ω . Meanwhile, by using the global C^s estimate for the solution to the fractional Laplacian, we have $v_h \in C^s(\mathbb{R}^n)$ whenever $h \in C_c^\infty(\Omega_e)$. Thus, by the continuity of v_h , there must exist a constant $c_h > 0$ such that $v_h \geq c_h > 0$ in $\bar{\Omega}$.

Now, let us plug the s -harmonic functions v_g to be the localized potentials $\{v^k\}$ and $v_h > 0$ into (3.3) such that

$$\begin{aligned} 0 &\leq \int_{\Omega} (q_1 - q_2) |v^k|^m v_h dx \\ &\leq -\delta c_h \int_M |v^k|^m dx \\ &\quad + \|q_1 - q_2\|_{L^\infty(\Omega)} \|v_h\|_{L^\infty(\Omega)} \int_{\Omega \setminus M} |v^k|^m dx \\ &\rightarrow -\infty, \end{aligned}$$

as $k \rightarrow \infty$.

The preceding arguments yield a contradiction. This implies that that $q_1 \geq q_2$ in Ω in both cases (a) and (b). Therefore, we conclude the if-and-only-if monotonicity relations (1.6) holds. \square

Corollary 4.1. *Let $\Omega \subset \mathbb{R}^n$, $n \geq 1$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $0 < s < 1$. Let $m \geq 2$, $m \in \mathbb{N}$. Let $q_1, q_2 \in L^\infty(\Omega)$, and Λ_{q_j} be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + q_j u^m = 0$ in Ω for $j = 1, 2$. Then we have*

$$q_1 = q_2 \text{ in } \Omega \quad \text{if and only if} \quad (D_0^m \Lambda_{q_1})_0 = (D_0^m \Lambda_{q_2})_0.$$

Proof. The results follows immediately from Theorem 1.1. \square

Remark 4.2. *We want to point out that:*

- (a) *The if-and-only-if monotonicity relations has been shown by Theorem 1.1 for general potentials $q_1, q_2 \in L^\infty(\Omega)$, without any sign constraints. For the (linear) fractional Schrödinger equation, the monotonicity relations can be proved by using the Lowner order (see [HL20, HPS19a]), which involves more functional analysis techniques in the arguments. We also refer readers to the further study [HPS19b] for the local case.*
- (b) *Corollary 4.1 is derived via the monotonicity method (Theorem 1.1). In fact, in order to determine $q_1 = q_2$ in Ω , one can only consider the condition of the original DN maps $\Lambda_{q_1} = \Lambda_{q_2}$ in the exterior domain. The proof is based on the higher order linearization and the Runge approximation for the fractional Laplacian, which needs to prove $(D_0^m \Lambda_{q_1})_0 = (D_0^m \Lambda_{q_2})_0$ by*

assuming $\Lambda_{q_1} = \Lambda_{q_2}$. For more details in different approaches, we refer the reader to [LL20].

4.2. A monotonicity-based reconstruction formula. In the end of this section, let us demonstrate a proof of the constructive uniqueness for the potential $q \in L^\infty(\Omega)$ of the fractional semilinear elliptic equation (1.1). Inspired by [HL19, HL20], we will show that the potential $q \in L^\infty(\Omega)$ can be reconstructed from the DN map Λ_q by testing Λ_ψ , where ψ is a *simple function*.

To this end, let M be a measurable set, and M is called a *density one set* if it is non-empty, measurable and has Lebesgue density 1 for all $x \in M$. The set of density one simple functions is defined by

$$\Sigma := \left\{ \psi = \sum_{j=1}^m a_j \chi_{M_j} : a_j \in \mathbb{R}, M_j \subseteq \Omega \text{ is a density one set} \right\},$$

Notice that every simple function agrees with a density one simple function almost everywhere due to the Lebesgue's density theorem. For our purposes, it is important to control the values on measure zero sets since these values might still affect the supremum when the supremum is taken over uncountably many functions.

We have the following constructive global uniqueness result.

Theorem 4.1. *Let $n \geq 1$, $\Omega \subset \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$, and $s \in (0, 1)$. Let $q \in L^\infty(\Omega)$ and Λ_q be the DN maps of the semilinear elliptic equations $(-\Delta)^s u + qu^m = 0$ in Ω , where $m \geq 2$, $m \in \mathbb{N}$. A potential $q = q(x)$ can be uniquely recovered by $(D^m \Lambda_q)_0$ via the following formula*

$$(4.3) \quad \begin{aligned} q(x) = & \sup \{ \psi(x) : \psi \in \Sigma, (D^m \Lambda_\psi)_0 \leq (D^m \Lambda_q)_0 \} \\ & + \inf \{ \psi(x) : \psi \in \Sigma, (D^m \Lambda_\psi)_0 \geq (D^m \Lambda_q)_0 \}, \end{aligned}$$

for all $x \in \Omega$.

Remark 4.3. *For the local case $s = 1$ and $m = 2$, the reconstruction formula for the potential $q(x)$ has been studied in [LLLS20a, Corollary 3.1]¹. The reconstruction formula was using the known the Calderón exponential solutions [Cal80] for the Laplace equation.*

To prove Theorem 4.1, let us adapt the following lemma which was shown in [HL20, Lemma 4.4].

Lemma 4.4 (Simple function approximation). *For any function $q \in L^\infty(\Omega)$, and $x \in \Omega$ a.e., we have that*

$$\max\{q(x), 0\} = \sup\{\psi(x) : \psi \in \Sigma \text{ with } \psi \leq q\}.$$

With the preceding lemma at hand, we can prove Theorem 4.1.

Proof of Theorem 4.1. Via Lemma 4.4 and Theorem 1.1, the potential $q \in L^\infty(\Omega)$ can be reconstructed by

$$\begin{aligned} q(x) &= \max\{q(x), 0\} - \max\{-q(x), 0\} \\ &= \sup\{\psi(x) : \psi \in \Sigma, \psi \leq q\} - \sup\{\psi(x) : \psi \in \Sigma, \psi \leq -q\} \\ &= \sup\{\psi(x) : \psi \in \Sigma, \psi \leq q\} + \inf\{\psi(x) : \psi \in \Sigma, \psi \geq q\} \\ &= \sup\{\psi(x) : \psi \in \Sigma, (D^m \Lambda_\psi)_0 \leq (D^m \Lambda_q)_0\} \\ &\quad + \inf\{\psi(x) : \psi \in \Sigma, (D^m \Lambda_\psi)_0 \geq (D^m \Lambda_q)_0\}, \end{aligned}$$

for almost everywhere $x \in \Omega$. This shows (4.3) holds for almost everywhere $x \in \Omega$. This completes the proof. \square

¹In fact, the reconstruction formula in [LLLS20a, Corollary 3.1] also holds for general $m \geq 2$ with $m \in \mathbb{N}$ in any bounded Euclidean domain $\Omega \subset \mathbb{R}^n$.

4.3. Inclusion detection by the monotonicity test. In this subsection, we will prove the second main result of this paper. The proof is also based on the if-and-only-if monotonicity relations (Theorem 1.1), which can be regarded as an application of the converse monotonicity relation. Recall that the testing operator $T_M : H^s(\Omega_e)^m \rightarrow H^s(\Omega)^*$ is defined by

$$\langle (T_M)(g, \dots, g), h \rangle = \int_M v_g^m v_h dx,$$

where v_g and v_h are s -harmonic in Ω with $v_g = g$ and $v_h = h$ in Ω_e , respectively.

Proof of Theorem 1.2. Let $\text{supp}(q - q_0) \subset C$, then there must exist some (large) constant $\alpha > 0$ such that

$$(4.4) \quad -\alpha\chi_C \leq q - q_0 \leq \alpha\chi_C.$$

By using Theorem 1.1, we know that (4.4) is equivalent to

$$(4.5) \quad (D^m \Lambda_{q_0 - \alpha\chi_C})_0 \leq (D^m \Lambda_q)_0 \leq (D^m \Lambda_{q_0 + \alpha\chi_C})_0.$$

Furthermore, via the identity for the m -th order derivative of the DN map (2.20), the elements $(D^m \Lambda_{q_0 \pm \alpha\chi_C})_0$ in (4.5) can be written as

$$(4.6) \quad \begin{aligned} & \langle (D^m \Lambda_{q_0 \pm \alpha\chi_C})_0(g, \dots, g), h \rangle \\ &= \int_{\Omega} (q_0 \pm \alpha\chi_C) v_g^m v_h dx \\ &= \int_{\Omega} q_0 v_g^m v_h dx \pm \alpha \int_C v_g^m v_h dx \\ &= \langle (D^m \Lambda_{q_0})_0(g, \dots, g), h \rangle \pm \alpha \langle T_M(g, \dots, g), h \rangle, \end{aligned}$$

where we have used the definition (1.7). Combining (4.5) and (4.6), one obtains

$$(4.7) \quad (D^m \Lambda_{q_0})_0 - \alpha T_C \leq (D^m \Lambda_q)_0 \leq (D^m \Lambda_{q_0})_0 + \alpha T_C,$$

provided that the condition (4.4) holds.

We next prove the converse part that if there exists some $\alpha > 0$ such that (4.7) holds, then we must have $\text{supp}(q - q_0) \subset C$. Suppose (4.7) holds, then Theorem 1.1 implies that

$$-\alpha\chi_C \leq q - q_0 \leq \alpha\chi_C.$$

The above inequality already shows that $q - q_0 = 0$ in $\Omega \setminus C$, which infers that $\text{supp}(q - q_0) \subset C$ as desired. Hence, the assertion is proved by the monotonicity test. \square

Note that in the statement of Theorem 1.2, we do not need to assume the definite case, i.e., either $q \geq q_0$ or $q \leq q_0$ in Ω . We will demonstrate that it is enough to test open sets to reconstruct the *inner support* for either $q \geq q_0$ or $q \leq q_0$.

Definition 4.5. *The inner support $\text{inn supp}(\phi)$ of a measurable function $\phi : \Omega \rightarrow \mathbb{R}$ is the union of all open sets $U \subseteq \Omega$, for which the essential infimum $\text{ess inf}_{x \in U} |\phi(x)|$ is positive.*

Theorem 4.2. *Let $q_0, q \in L^\infty(\Omega)$ be potentials. For the definite case, we have:*

- (a) *Let $q \leq q_0$. For every open set $B \subseteq \Omega$ and every $\alpha > 0$*

$$(4.8) \quad q \leq q_0 - \alpha\chi_B \implies (D^m \Lambda_q)_0 \leq (D^m \Lambda_{q_0})_0 - \alpha T_B \implies B \subseteq \text{supp}(q - q_0).$$

Thus,

$$\begin{aligned} & \text{inn supp}(q - q_0) \\ & \subseteq \bigcup \{B \subseteq \Omega \text{ open ball} : \exists \alpha > 0 : (D^m \Lambda_q)_0 \leq (D^m \Lambda_{q_0})_0 - \alpha T_B\} \\ & \subseteq \text{supp}(q - q_0). \end{aligned}$$

(b) Let $q \geq q_0$. For every open set $B \subseteq \Omega$ and every $\alpha > 0$

$$(4.9) \quad q \geq q_0 + \alpha \chi_B \implies (D^m \Lambda_q) \geq (D^m \Lambda_{q_0})_0 + \alpha T_B,$$

and

$$(4.10) \quad (D^m \Lambda_q)_0 \geq (D^m \Lambda_{q_0})_0 + \alpha T_B \implies q \geq q_0 + \alpha \chi_B.$$

Thus,

$$\begin{aligned} & \text{inn supp}(q - q_0) \\ & = \bigcup \{B \subseteq \Omega \text{ open ball} : \exists \alpha > 0 : (D^m \Lambda_q)_0 \geq (D^m \Lambda_{q_0})_0 + \alpha T_B\}. \end{aligned}$$

Proof. (a) If $q \leq q_0 - \alpha \chi_B$, by using Theorem 1.1 and adapting the same trick as in the proof of Theorem 1.2, we have that

$$(D^m \Lambda_q)_0 - (D^m \Lambda_{q_0})_0 \leq -\alpha T_B.$$

Moreover, if $(D^m \Lambda_q)_0 \leq (D^m \Lambda_{q_0})_0 \leq -\alpha T_B$, by Theorem 1.1 and Theorem 1.2 again, that there exists $c > 0$ with

$$\alpha T_B \leq (D^m \Lambda_{q_0})_0 - (D^m \Lambda_q)_0 = \int_{\Omega} (q_0 - q) v_g^m v_h \, dx,$$

which implies

$$(4.11) \quad \int_{\Omega} (\alpha \chi_B v_g^m v_h - \|q - q_0\|_{L^\infty(\Omega)} \chi_{\text{supp}(q - q_0)} v_g^m v_h) \, dx \leq 0.$$

With the localized potential for the fractional Laplacian at hand (similar to the proof of Theorem 1.1), the inequality (4.11) must yield

$$\alpha \chi_B \leq \|q - q_0\|_{L^\infty(\Omega)} \chi_{\text{supp}(q - q_0)}.$$

(b) The results (4.9) and (4.10) are simple applications of Theorem 1.1. \square

5. LIPSCHITZ STABILITY WITH FINITELY MANY MEASUREMENTS

In the last section of this paper, we prove Theorem 1.4, and the ideas of the proof are from [Har19, HL20].

Proof of Theorem 1.3. Let us divide the proof into several steps.

Step 1. Fundamental estimates

For $q_1 \neq q_2$ in Ω with $q_1, q_2 \in \mathcal{Q}$, we want to show that

$$(5.1) \quad \frac{\|(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0\|_*}{\|q_1 - q_2\|_{L^\infty(\Omega)}} \geq \inf_{\kappa \in \mathcal{K}} \sup_{\substack{g, h \in C_c^\infty(\Omega_e), \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa, g, h),$$

where $\Phi : \mathcal{K} \times C_c^\infty(\Omega_e) \times C^\infty(\Omega_e)$ is given by

$$\Phi(\kappa, g, h) := \max \{ \langle (D^m \Lambda_\kappa)_0(g, \dots, g), h \rangle \},$$

and $\mathcal{K} = \{\kappa \in \text{span}\mathcal{Q} : \|\kappa\|_{L^\infty(\Omega)} = 1\}$ is a finite-dimensional subspace of $L^\infty(\Omega)$. By the definition of $\|\cdot\|_*$, we have

$$\|(D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0\|_* = \sup_{\substack{g, h \in C_c^\infty(\Omega_e), \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \langle (D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0(g, \dots, g), h \rangle$$

and

$$\begin{aligned} & |\langle (D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0(g, \dots, g), h \rangle| \\ &= \max \{ \langle (D^m \Lambda_{q_1})_0 - (D^m \Lambda_{q_2})_0(g, \dots, g), h \rangle, \langle (D^m \Lambda_{q_2})_0 - (D^m \Lambda_{q_1})_0(g, \dots, g), h \rangle \} \\ &= \|q_1 - q_2\|_{L^\infty(\Omega)} \max \left\{ \int_{\Omega} \frac{q_1 - q_2}{\|q_1 - q_2\|_{L^\infty(\Omega)}} v_g^m v_h dx, \int_{\Omega} \frac{q_2 - q_1}{\|q_1 - q_2\|_{L^\infty(\Omega)}} v_g^m v_h dx \right\} \\ &= \|q_1 - q_2\|_{L^\infty(\Omega)} \Phi \left(\frac{q_1 - q_2}{\|q_1 - q_2\|_{L^\infty(\Omega)}}, g, h \right), \end{aligned}$$

where we have utilized the integral identity (3.3) and the linearity of the m -th order derivative of the DN map Λ_q in the above computations. Therefore, the claim (5.1) must hold.

Step 2. Positive lower bound of Φ

We next show that there exists $\widehat{\kappa} \in \mathcal{K}$ such that

$$\inf_{\kappa \in \mathcal{K}} \sup_{\substack{g, h \in C_c^\infty(\Omega_e), \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa, g, h) = \sup_{\substack{g, h \in C_c^\infty(\Omega_e), \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\widehat{\kappa}, g, h).$$

The fact directly follows by the smoothness of the DN map (see Section 2) such that the function

$$\kappa \mapsto \sup_{\substack{g, h \in C_c^\infty(\Omega_e), \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa, g, h)$$

is lower semicontinuous and its minimum can be achieved over the compact set \mathcal{K} (a finite dimensional subspace of $L^\infty(\Omega)$).

Finally, since $q_1 - q_2 \not\equiv 0$ in Ω , by applying the localized potentials for s -harmonic functions (Corollary 3.4), there must exist $g, h \in H^s(\Omega_e)$ such that

$$(5.2) \quad \text{either} \quad \int_{\Omega} \kappa v_g^m v_h dx > 0 \quad \text{or} \quad \int_{\Omega} \kappa v_g^m v_h dx < 0,$$

where we have utilized the fact that $\kappa \in \text{span}\mathcal{Q}$. Hence, we can obtain

$$c_0 := \sup_{\substack{g, h \in C_c^\infty(\Omega_e), \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa, g, h) > 0, \quad \text{for any } \kappa \in \mathcal{K},$$

which completes the proof. \square

It remains to prove our last theorem in the paper.

Proof of Theorem 1.4. By using

$$\begin{aligned} & \|P'_{H_\ell} ((D^m \Lambda_{q_2})_0 - (D^m \Lambda_{q_1})_0) P_{H_\ell}\|_* \\ &= \sup_{g, h \in H_\ell} |\langle ((D^m \Lambda_{q_2})_0 - (D^m \Lambda_{q_1})_0)(g, \dots, g), h \rangle|, \end{aligned}$$

and applying the preceding arguments, for any $\ell \in \mathbb{N}$, there exists $\kappa_\ell \in \mathcal{K}$ such that

$$(5.3) \quad \frac{\|P'_{H_\ell} ((D^m \Lambda_{q_2})_0 - (D^m \Lambda_{q_1})_0) P_{H_\ell}\|_*}{\|q_1 - q_2\|_{L^\infty(\Omega)}} \geq \sup_{\substack{g, h \in H_\ell, \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa_\ell, g, h).$$

Notice that the right hand side of (5.3) is monotonically increasing in $\ell \in \mathbb{N}$, since $H_1 \subseteq H_2 \subseteq \dots \subseteq H_\ell \subset \dots \subseteq H^s(\Omega_e)$. Therefore, Theorem 1.4 holds if we can prove that there is $\ell \in \mathbb{N}$ such that

$$(5.4) \quad \sup_{\substack{g, h \in H_\ell, \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa, g, h) > 0, \quad \text{for all } \kappa \in \mathcal{K}.$$

We prove the claim (5.4) by a contradiction argument, i.e., there must exist a sequence $(\kappa_\ell)_{\ell \in \mathbb{N}} \subset \mathcal{K}$ such that

$$\sup_{\substack{g, h \in H_\ell, \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa_\ell, g, h) \leq 0, \quad \text{for } \ell \geq m,$$

for any $m \in \mathbb{N}$. After passing a subsequence (if necessary), by the compactness (due to the finite dimensional assumption of \mathcal{Q}), we can assume that there exists an element $\kappa_\infty \in \mathcal{K}$ such that $\lim_{\ell \rightarrow \infty} \kappa_\ell = \kappa_\infty$ and

$$\sup_{\substack{g, h \in H_m, \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa_\infty, g, h) \leq \lim_{\ell \rightarrow \infty} \sup_{\substack{g, h \in H_m, \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa_\ell, g, h) \leq 0,$$

where we have utilized the lower semicontinuous of the function

$$\kappa \rightarrow \sup_{\substack{g, h \in H_\ell, \\ \|g\|_{H^s} = \|h\|_{H^s} = 1}} \Phi(\kappa, g, h).$$

On the other hand, by the continuity, we must have

$$\Phi(\kappa_\infty, g, h) \leq 0, \quad \text{for all } g, h \in \overline{\bigcup_{m \in \mathbb{N}} H_m} = H^s(\Omega_e),$$

which contradicts to (5.1) in the previous proof. This proves that (5.4) must hold for some $\ell \in \mathbb{N}$ as desired. \square

APPENDIX A. THE L^p -ESTIMATE FOR THE FRACTIONAL LAPLACIAN

Let us review the other estimates for solutions to the fractional Laplacian: The L^p estimate. Before doing so, let us recall some fundamental properties for the *Riesz potential*.

Proposition A.1 (Riesz potential). *For $0 < s < 1$ with $n > 2s$. Let V and F satisfy*

$$V = (-\Delta)^{-s} F \text{ in } \mathbb{R}^n,$$

in the sense that V is the Riesz potential of order $2s$ of the function F .

- (a) *If $F \in L^1(\mathbb{R}^n)$, then there exists a constant $C > 0$ depending only on n and s such that*

$$\|V\|_{L^p_w(\mathbb{R}^n)} \leq C \|F\|_{L^1(\mathbb{R}^n)},$$

where L^p_w denotes the weak- L^p norm and $p = \frac{n}{n-2s}$.

- (b) *For $r \in (1, \frac{n}{2s})$, $F \in L^r(\mathbb{R}^n)$, then there exists a constant $C > 0$ depending only on n , s , and r such that*

$$\|V\|_{L^p(\mathbb{R}^n)} \leq C \|F\|_{L^r(\mathbb{R}^n)},$$

where $p = \frac{nr}{n-2rs}$.

- (c) *For $r \in (\frac{n}{2s}, \infty)$, then there exists a constant $C > 0$ depending only on n , s , and r such that*

$$[u]_{C^\alpha(\mathbb{R}^n)} \leq C \|F\|_{L^r(\mathbb{R}^n)},$$

where $\alpha = 2s - \frac{n}{p}$ and $[u]_{C^\alpha(\mathbb{R}^n)}$ is the seminorm given in Section 2.

Proof. Parts (a) and (b) are classical results for the Riesz potential, and the proof can be found in Stein's book [Ste16, Chapter V]. For (c), we refer readers to [Ste16, p.164] and [GCC04]. \square

Furthermore, we have the following Hölder estimate for the fractional Laplacian, which was shown in [ROS14b, Proposition 1.7]. We state the result in the following proposition and the proof can be found in [ROS14b].

Proposition A.2 (C^β -estimate). *For $n \geq 1$, $0 < s < 1$, let $\Omega \subseteq \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$. Let $h \in C^\alpha(\Omega_e)$ for some $\alpha \in (0, 1)$. Let w be the solution of*

$$\begin{cases} (-\Delta)^s w = 0 & \text{in } \Omega, \\ w = h & \text{in } \Omega_e. \end{cases}$$

Then the solution $w \in C^\beta(\mathbb{R}^n)$, where $\beta = \min\{s, \alpha\}$, and

$$\|w\|_{C^\beta(\mathbb{R}^n)} \leq C \|h\|_{C^\alpha(\Omega_e)},$$

for some constant $C > 0$ depending only on Ω , α , and s .

The following proposition was also proved in [ROS14b], which is an important result in the proof of our Runge approximation (Theorem 3.2). We state the result and prove it for the sake of completeness. The proof is based on the preceding properties of the Riesz potential, the maximum principle for the fractional Laplacian and the C^β -estimate (Proposition A.2).

Proposition A.3. *For $n \geq 1$, $0 < s < 1$, let $\Omega \subseteq \mathbb{R}^n$ be a bounded domain with $C^{1,1}$ boundary $\partial\Omega$. For $F \in L^r(\Omega)$, let v be the solution of*

$$(A.1) \quad \begin{cases} (-\Delta)^s v = F & \text{in } \Omega, \\ v = 0 & \text{in } \Omega_e, \end{cases}$$

then we have:

- (a) *Let $n > 2s$, $r = 1$, and $p \in [1, \frac{n}{n-2s})$ be an arbitrary number, then there exists a constant $C > 0$ independent of v and F such that*

$$\|v\|_{L^p(\Omega)} \leq C \|F\|_{L^1(\Omega)}.$$

- (b) *Let $n > 2s$, $r \in (1, \frac{n}{2s})$ and $p = \frac{nr}{n-2rs}$, then there exists a constant $C > 0$ independent of v and F such that*

$$\|v\|_{L^p(\Omega)} \leq C \|F\|_{L^r(\Omega)}.$$

- (c) *Let $n > 2s$, $r \in (\frac{n}{2s}, \infty)$, and $\beta = \min\{s, 2s - \frac{n}{r}\}$, then there exists a constant $C > 0$ independent of v and F such that*

$$\|v\|_{C^\beta(\Omega)} \leq C \|F\|_{L^r(\Omega)}.$$

- (d) *Let $n = 1$, $s \in [\frac{1}{2}, 1)$, $r \geq 1$, and any $p < \infty$, then there exists a constant $C > 0$ independent of v and F such that*

$$\|v\|_{L^p(\Omega)} \leq C \|F\|_{L^r(\Omega)}.$$

Proof. (a) Let us extend the function F by 0 outside Ω , and we still denote the function as F . Let V be the solution of

$$(-\Delta)^s V = |F| \text{ in } \mathbb{R}^n,$$

so that $V = (-\Delta)^{-s}|F|$ in \mathbb{R}^n , where $(-\Delta)^{-s}|F|$ is the Riesz potential of $|F|$. By the definition of the Riesz potential, we have $V \geq 0$ in Ω_e . Via the maximum

principle, we obtain that $|v| \leq V$ in Ω . By applying Proposition A.1, one can see that

$$\|v\|_{L_w^q(\Omega)} \leq \|V\|_{L_w^q(\Omega)} \leq C\|F\|_{L^1(\Omega)},$$

if $F \in L^1(\Omega)$ and for some constant $C > 0$ independent of v and F . Thus, one has

$$\|v\|_{L^r(\Omega)} \leq C\|F\|_{L^1(\Omega)},$$

for some constant $C > 0$ independent of v and F . This proves (a).

(b) Similarly, the proof of (b) can be completed by using the result (b) in Proposition A.1 and the maximum principle for the fractional Laplacian as before. Furthermore, when $r = \frac{n}{2s}$, it is easy to see that $F \in L^r(\Omega) \subset L^{\tilde{r}}(\Omega)$, for any $\tilde{r} \in [1, r]$ (since Ω is bounded). We still have the L^p estimate for the solution in the borderline case $r = \frac{n}{2s}$.

(c) Let us write $v = \tilde{v} + w$, where \tilde{v} and w are given by

$$(A.2) \quad \tilde{v} = (-\Delta)^{-s}F \text{ in } \mathbb{R}^n,$$

and

$$(A.3) \quad \begin{cases} (-\Delta)^s w = 0 & \text{in } \Omega, \\ w = \tilde{v} & \text{in } \Omega_e. \end{cases}$$

By using (A.2) and Proposition A.1 (c), there exists a constant $C > 0$ depending only on n , s , and r such that

$$[\tilde{v}]_{C^\alpha(\mathbb{R}^n)} \leq C\|F\|_{L^r(\mathbb{R}^n)}, \quad \text{where } \alpha = 2s - \frac{n}{r}.$$

Since Ω is bounded and F is compactly supported, one has \tilde{v} decays at infinity. This implies that

$$(A.4) \quad \|\tilde{v}\|_{C^\alpha(\mathbb{R}^n)} \leq C\|F\|_{L^r(\mathbb{R}^n)}, \quad \text{where } \alpha = 2s - \frac{n}{r},$$

for some constant $C > 0$ depending only on n , s , r and Ω .

On the other hand, we can apply Proposition A.2 to derive the Hölder estimate for the solution w of (A.3) that

$$(A.5) \quad \|w\|_{C^\beta(\mathbb{R}^n)} \leq C\|\tilde{v}\|_{C^\alpha(\Omega_e)},$$

for some constant $C > 0$ depending only on Ω , α , and s , where

$$\beta = \min\{\alpha, s\} = \min\left\{s, 2s - \frac{n}{r}\right\}.$$

Combining with (A.4) and (A.5), we can obtain the Hölder estimate for the solution $v = \tilde{v} + w$ such that (c) holds. Moreover, since $v \in C^\beta(\overline{\Omega})$ with $v = 0$ in Ω_e , we must have $v \in L^p(\mathbb{R}^n)$ for any $p \geq 1$.

(d) Notice that for $s < \frac{1}{2}$, we have $n = 1 > 2s$ automatically, such that the case (d) holds by applying the results either (a) or (b). On the other hand, for the case $1 = n \leq 2s$, this implies that $\frac{1}{2} \leq s < 1$. Under this situation, any bounded domain is of the form $\Omega = (a, b) \subset \mathbb{R}$. By [BGR61], the Green function $G(x, y)$ for the exterior value problem (A.1) is explicit. Furthermore, $G(\cdot, y) \in L^\infty(\Omega)$ when $s > \frac{1}{2}$ and $G(x, y) \in L^r(\Omega)$ for any $r < \infty$ when $s = \frac{1}{2}$. Therefore, one has

$$\|v\|_{L^\infty(\Omega)} \leq C\|F\|_{L^1(\Omega)},$$

for some constant $C > 0$ independent of v and F , where $n < 2s$. For the case $n = 2s$, we have either

$$\|v\|_{L^p(\Omega)} \leq C\|F\|_{L^1(\Omega)}, \quad \text{for all } p < \infty,$$

or

$$\|v\|_{L^\infty(\Omega)} \leq C\|F\|_{L^r(\Omega)}, \quad \text{for } r > 1,$$

for some constant $C > 0$ independent of v and F . \square

Remark A.4. *From the L^p estimate of s -harmonic functions, we have:*

- (a) *No matter what exponent $r \geq 1$ and what space dimension n are, for any $F \in L^r(\Omega)$ with $\Omega \subset \mathbb{R}^n$ in the statement of Proposition A.3, then we can always conclude that the solution v of (A.1) must belong to $L^p(\mathbb{R}^n)$, for some $p > 1$.*
- (b) *Moreover, since the domain Ω is bounded in \mathbb{R}^n , then we can confine the exponent p in the region $p \in (1, 2)$. The condition $p \in (1, 2)$ plays an essential role in order to prove Proposition 3.3 (see [CMR20, Section 4] for more detailed discussions about the strong uniqueness of the s -harmonic function). Meanwhile, we also need to use the L^p -estimate to prove the Runge approximation via the strong uniqueness for the fractional Laplacian in Section 3.*

APPENDIX B. THE MAXIMUM PRINCIPLE

We review the known maximum principle for the fractional Laplacian in the end of this work. These results were shown in [RO16, BV16] for the fractional Laplacian equation and [LL19, LL20] for the fractional Schrödinger equation. For the sake of convenience, we state the results as follows.

Proposition B.1 (The maximum principle). *Let $\Omega \subset \mathbb{R}^n$, $n \geq 1$ be a bounded domain with Lipschitz boundary $\partial\Omega$, and $0 < s < 1$. Let $v \in H^s(\mathbb{R}^n)$ be the unique solution of*

$$\begin{cases} (-\Delta)^s v = F & \text{in } \Omega, \\ v = g & \text{in } \Omega_e. \end{cases}$$

Suppose that $0 \leq F \in L^\infty(\Omega)$ in Ω and $0 \leq g \in L^\infty(\Omega_e)$ in Ω_e . Then $v \geq 0$ in Ω . Moreover, if $g \not\equiv 0$ in Ω_e , then $v > 0$ in Ω .

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DEPARTMENT OF APPLIED MATHEMATICS, NATIONAL CHIAO TUNG UNIVERSITY, TAIWAN
 Email address: yihuanlin3@gmail.com